

The Construction and the *Mallat* Algorithm of Biorthogonal Two Dimensional Four-Direction Multi-Wavelet with Dilation Factor a

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Abstract

Through the concept of two dimensional four-direction multi-scaling function and two dimensional four-direction multi-wavelet, the two dimensional four-direction orthogonal multi-wavelet with dilation factor two is generalized to two dimensional biorthogonal multi-wavelet with dilation factor a . Furthermore, the construction algorithm of two dimensional biorthogonal multi-scaling function and multi-wavelet with dilation factor a is given. Finally, the *Mallat* algorithm of two dimensional four-direction multi-wavelet with dilation factor a is studied.

Keywords

Two Dimensional Four-Direction Multi-Scaling Function, Two Dimensional Four-Direction Multi-Wavelet, Biorthogonality, *Mallat* Algorithm

a 尺度二维双向双正交多小波的构造和*Mallat*算法

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摘要

通过二维四向多加细函数以及二维四向多小波的概念, 推广二尺度二维四向正交多小波为 a 尺度二维四向双正交多小波, 更进一步对于 a 尺度二维四向双正交多加细函数和多小波的构造算法做出了相应给出, 最后研究了 a 尺度二维四向多小波的Mallat算法。

关键词

二维四向多加细函数, 二维四向多小波, 双正交性, Mallat算法

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1. 引言

小波分析是这些年来发展起来的一门新兴数学理论以及方法, 在信号处理, 语音处理, 图像处理, 数据压缩, 微分方程求解, 地震勘探等各个领域有着广泛的应用。Haar 小波是同时具有正交性, 对称性和紧支撑性的单小波, 但是其它单小波并不能具有这样好的性质, 所以人们引入了多小波。从带宽来看, 二尺度小波高频端的带宽比较窄, 那么从小波分析的效果来看二尺度小波效果相对比较差, 所以人们提出了 a 尺度小波。双向小波的概念是杨守志等人首先提出的[1], 后来进一步得出了一系列好的理论和结果[2][3]。本文在引入二维四向多小波基础上, 建立了 a 尺度二维四向多加细函数和 a 尺度二维四向多小波, 给出了 a 尺度二维四向多加细函数和 a 尺度二维四向多小波的正交和双正交准则, 以及它们的构造算法, 最后讨论了 a 尺度二维四向多小波的分解与重构的Mallat 算法。

2. 预备知识

先给出文章要提到的记号: \mathbf{C}^N 表示 N 维复欧几里德空间。 I 表示 $r \times r$ 阶单位矩阵, \mathbf{O} 表示 $r \times r$ 阶零矩阵, \mathbf{T} 表示向量或矩阵的转置, 向量值函数信号空间 $\mathbf{L}^2(\mathbf{R}, \mathbf{C}^N) \cong \mathbf{L}^2$ 可以表示为

$\mathbf{L}^2(\mathbf{R}, \mathbf{C}^N) \cong \left\{ F(t) = (f_1(t), f_2(t), \dots, f_N(t))^T : t \in \mathbf{R}, f_k(t) \in \mathbf{L}^2(\mathbf{R}), k = 1, 2, \dots, N \right\}$, (根据文献[4])对于 $F(t) \in \mathbf{L}^2(\mathbf{R}, \mathbf{C}^N)$ 它的积分和 Fourier 变换分别定义为

$$\int_{\mathbf{R}} F(t) dt \cong \left[\int_{\mathbf{R}} f_1(t) dt, \int_{\mathbf{R}} f_2(t) dt, \dots, \int_{\mathbf{R}} f_N(t) dt \right]^T$$

和

$$F(\omega) \cong \left[\int_{\mathbf{R}} f_1(t) e^{-i\omega t} dt, \int_{\mathbf{R}} f_2(t) e^{-i\omega t} dt, \dots, \int_{\mathbf{R}} f_N(t) e^{-i\omega t} dt \right]^T$$

若 F 和 G 都是一元函数空间, 它们两个的基底分别为 $\{f_k(x)\}_{k \in \mathbf{Z}}$ 和 $\{g_k(x)\}_{k \in \mathbf{Z}}$, 二元函数空间 H 表示为 $H = F \otimes G$ 是 F 和 G 的张量积空间, H 的基底可以表示为 $\{f_k(x)g_k(x)\}_{k \in \mathbf{Z}}$ 。

定义 $\{V_j\}$ 的张量积空间为 $V_j^2 = V_j \otimes V_j = \{f_k(x)g_k(x)\}_{f_k(x), g_k(x) \in V_j}$, 而 $\{V_j\}$ 表示为由一元尺度函数 φ 生成的一个正交多分辨分析。那么关于二元函数 $f(x, y) \in \mathbf{L}^2(\mathbf{R}^2)$, 引入记号 $\varphi(x, y) = \varphi(x)\varphi(y)$ 。

二维双向加细尺度函数

基于双向尺度函数的概念, 现在假设有 $r+1$ 个双向尺度函数 $\varphi_1(x), \varphi_2(x), \dots, \varphi_r(x), \varphi(y) \in L^2(\mathbf{R})$, 记 $\Phi(x) = [\varphi_1(x), \varphi_2(x), \dots, \varphi_r(x)]^\top$, 那么通过 $\Phi(x)$ 和 $\varphi(y)$ 的张量积来构造二维四向多尺度函数。假设双向加细函数 $\varphi_i(x)$ 和 $\varphi(y)$ 都符合细分方程

$$\varphi_i(x) = \sum_k \mathbf{P}_{1,k}^+ \varphi_i(ax - k) + \sum_k \mathbf{P}_{1,k}^- \varphi_i(k - ax), \quad i = 1, \dots, r$$

$$\varphi(y) = \sum_k \mathbf{P}_{2,k}^+ \varphi(ay - k) + \sum_k \mathbf{P}_{2,k}^- \varphi(k - ay)$$

设 $\Phi(x, y) = \varphi_i(x)\varphi(y)$, 就能得出

$$\begin{aligned} \Phi(x, y) &= \left\{ \sum_k \mathbf{P}_{1,k}^+ \varphi_i(ax - k) + \sum_k \mathbf{P}_{1,k}^- \varphi_i(k - ax) \right\} \otimes \left\{ \sum_l \mathbf{P}_{2,l}^+ \varphi(ay - l) + \sum_l \mathbf{P}_{2,l}^- \varphi(l - ay) \right\} \\ &= \sum_{k,l} \mathbf{P}_{1,k}^+ \mathbf{P}_{2,l}^+ \varphi_i(ax - k) \varphi(ay - l) + \sum_{k,l} \mathbf{P}_{1,k}^+ \mathbf{P}_{2,l}^- \varphi_i(ax - k) \varphi(l - ay) \\ &\quad + \sum_{k,l} \mathbf{P}_{1,k}^- \mathbf{P}_{2,l}^+ \varphi_i(k - ax) \varphi(ay - l) + \sum_{k,l} \mathbf{P}_{1,k}^- \mathbf{P}_{2,l}^- \varphi_i(k - ax) \varphi(l - ay) \\ &= \sum_{k,l} \mathbf{P}_{1,k}^+ \mathbf{P}_{2,l}^+ \varphi(ax - k, ay - l) + \sum_{k,l} \mathbf{P}_{1,k}^+ \mathbf{P}_{2,l}^- \varphi(ax - k, l - ay) \\ &\quad + \sum_{k,l} \mathbf{P}_{1,k}^- \mathbf{P}_{2,l}^+ \varphi(k - ax, ay - l) + \sum_{k,l} \mathbf{P}_{1,k}^- \mathbf{P}_{2,l}^- \varphi(k - ax, l - ay). \end{aligned}$$

从而根据适合的 $\{\mathbf{P}_{l,k}^{+,+}\}, \{\mathbf{P}_{l,k}^{+-}\}, \{\mathbf{P}_{l,k}^{-,+}\}, \{\mathbf{P}_{l,k}^{-,-}\}$, 就有

$$\begin{aligned} \Phi(x, y) &= \sum_{k,l} \mathbf{P}_{l,k}^{+,+} \varphi(ax - k, ay - l) + \sum_{k,l} \mathbf{P}_{l,k}^{+-} \varphi(ax - k, l - ay) \\ &\quad + \sum_{k,l} \mathbf{P}_{l,k}^{-,+} \varphi(k - ax, ay - l) + \sum_{k,l} \mathbf{P}_{l,k}^{-,-} \varphi(k - ax, l - ay). \end{aligned}$$

令 $\Phi(x, y) = \Phi(x) \cdot \varphi(y)$, 则

$$\Phi(x, y) = [\Phi_1(x, y), \Phi_2(x, y), \dots, \Phi_r(x, y)]^\top$$

那么就可以有 a 尺度多小波细分方程

$$\begin{aligned} \Phi(x, y) &= \sum_{k,l} \mathbf{P}_{l,k}^{+,+} \Phi(ax - k, ay - l) + \sum_{k,l} \mathbf{P}_{l,k}^{+-} \Phi(ax - k, l - ay) \\ &\quad + \sum_{k,l} \mathbf{P}_{l,k}^{-,+} \Phi(k - ax, ay - l) + \sum_{k,l} \mathbf{P}_{l,k}^{-,-} \Phi(k - ax, l - ay). \end{aligned} \tag{1}$$

接下来对(1)式进行 Fourier 变换就可以有

$$\begin{aligned} \hat{\Phi}(\omega_1, \omega_2) &= \mathbf{P}^{+,+} \left(\frac{\omega_1}{a}, \frac{\omega_2}{a} \right) \hat{\Phi} \left(\frac{\omega_1}{a}, \frac{\omega_2}{a} \right) + \mathbf{P}^{+-} \left(\frac{\omega_1}{a}, \frac{\omega_2}{a} \right) \hat{\Phi} \left(\frac{\omega_1}{a}, -\frac{\omega_2}{a} \right) \\ &\quad + \mathbf{P}^{-,+} \left(\frac{\omega_1}{a}, \frac{\omega_2}{a} \right) \hat{\Phi} \left(-\frac{\omega_1}{a}, \frac{\omega_2}{a} \right) + \mathbf{P}^{-,-} \left(\frac{\omega_1}{a}, \frac{\omega_2}{a} \right) \hat{\Phi} \left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a} \right), \end{aligned} \tag{2}$$

其中

$$\mathbf{P}^{+,+} \left(\frac{\omega_1}{a}, \frac{\omega_2}{a} \right) = \frac{1}{a^2} \sum_{k,l} \mathbf{P}_{k,l}^{+,+} e^{-i \left(\frac{\omega_1 k}{a} + \frac{\omega_2 l}{a} \right)},$$

$$\mathbf{P}^{+,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) = \frac{1}{a^2} \sum_{k,l} \mathbf{P}_{k,l}^{+,-} e^{-i\left(\frac{\omega_1 k}{a} + \frac{\omega_2 l}{a}\right)},$$

$$\mathbf{P}^{-,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) = \frac{1}{a^2} \sum_{k,l} \mathbf{P}_{k,l}^{-,+} e^{-i\left(\frac{\omega_1 k}{a} + \frac{\omega_2 l}{a}\right)},$$

$$\mathbf{P}^{-,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) = \frac{1}{a^2} \sum_{k,l} \mathbf{P}_{k,l}^{-,-} e^{-i\left(\frac{\omega_1 k}{a} + \frac{\omega_2 l}{a}\right)},$$

令

$$\mathbf{P}_{k,l}^{+,+} = \begin{bmatrix} \mathbf{P}_{1,k,l}^{+,+} & \mathbf{P}_{r,k,l}^{+,+} \\ 0 & \mathbf{P}_{r^2,k,l}^{+,+} \end{bmatrix}, \quad \mathbf{P}_{k,l}^{+,-} = \begin{bmatrix} \mathbf{P}_{1,k,l}^{+,-} & \mathbf{P}_{r,k,l}^{+,-} \\ 0 & \mathbf{P}_{r^2,k,l}^{+,-} \end{bmatrix},$$

$$\mathbf{P}_{k,l}^{-,+} = \begin{bmatrix} \mathbf{P}_{1,k,l}^{-,+} & \mathbf{P}_{r,k,l}^{-,+} \\ 0 & \mathbf{P}_{r^2,k,l}^{-,+} \end{bmatrix}, \quad \mathbf{P}_{k,l}^{-,-} = \begin{bmatrix} \mathbf{P}_{1,k,l}^{-,-} & \mathbf{P}_{r,k,l}^{-,-} \\ 0 & \mathbf{P}_{r^2,k,l}^{-,-} \end{bmatrix},$$

为双正, 正负和双负矩阵符号。下面对(1)进行变形有

$$\begin{aligned} \Phi(x, -y) &= \sum_{k,l} \mathbf{P}_{l,k}^{+,+} \Phi(x)(ax - k, -ay - l) + \sum_{k,l} \mathbf{P}_{l,k}^{+,-} \Phi(x)(ax - k, l + ay) \\ &\quad + \sum_{k,l} \mathbf{P}_{l,k}^{-,+} \Phi(x)(k - ax, -ay - l) + \sum_{k,l} \mathbf{P}_{l,k}^{-,-} \Phi(x)(k - ax, l + ay). \end{aligned} \quad (3)$$

$$\begin{aligned} \Phi(-x, y) &= \sum_{k,l} \mathbf{P}_{l,k}^{+,+} \Phi(x)(-ax - k, ay - l) + \sum_{k,l} \mathbf{P}_{l,k}^{+,-} \Phi(x)(-ax - k, l - ay) \\ &\quad + \sum_{k,l} \mathbf{P}_{l,k}^{-,+} \Phi(x)(ax + k, ay - l) + \sum_{k,l} \mathbf{P}_{l,k}^{-,-} \Phi(x)(ax + k, l - ay). \end{aligned} \quad (4)$$

$$\begin{aligned} \Phi(-x, -y) &= \sum_{k,l} \mathbf{P}_{l,k}^{+,+} \Phi(x)(-ax - k, -ay - l) + \sum_{k,l} \mathbf{P}_{l,k}^{+,-} \Phi(x)(-ax - k, l + ay) \\ &\quad + \sum_{k,l} \mathbf{P}_{l,k}^{-,+} \Phi(x)(ax + k, -ay - l) + \sum_{k,l} \mathbf{P}_{l,k}^{-,-} \Phi(x)(ax + k, l + ay). \end{aligned} \quad (5)$$

下面对(3)~(5)式都进行 Fourier 变换就有

$$\begin{aligned} \hat{\Phi}(\omega_1, -\omega_2) &= \mathbf{P}^{+,+}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \hat{\Phi}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) + \mathbf{P}^{+,-}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \hat{\Phi}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \\ &\quad + \mathbf{P}^{-,+}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \hat{\Phi}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) + \mathbf{P}^{-,-}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \hat{\Phi}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right), \end{aligned} \quad (6)$$

$$\begin{aligned} \hat{\Phi}(-\omega_1, \omega_2) &= \mathbf{P}^{+,+}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \hat{\Phi}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) + \mathbf{P}^{+,-}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \hat{\Phi}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \\ &\quad + \mathbf{P}^{-,+}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \hat{\Phi}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) + \mathbf{P}^{-,-}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \hat{\Phi}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right), \end{aligned} \quad (7)$$

$$\begin{aligned} \hat{\Phi}(-\omega_1, -\omega_2) &= \mathbf{P}^{+,+}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \hat{\Phi}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) + \mathbf{P}^{+,-}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \hat{\Phi}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \\ &\quad + \mathbf{P}^{-,+}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \hat{\Phi}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) + \mathbf{P}^{-,-}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \hat{\Phi}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right), \end{aligned} \quad (8)$$

根据(2)(6)~(8)式可以有, 令

$$\hat{\Gamma}(\omega_1, \omega_2) = \begin{bmatrix} \mathbf{P}^{+,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) & \mathbf{P}^{+,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) & \mathbf{P}^{-,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) & \mathbf{P}^{-,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \\ \mathbf{P}^{+,-}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) & \mathbf{P}^{+,+}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) & \mathbf{P}^{-,-}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) & \mathbf{P}^{-,+}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \\ \mathbf{P}^{-,+}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) & \mathbf{P}^{-,-}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) & \mathbf{P}^{+,+}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) & \mathbf{P}^{+,-}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \\ \mathbf{P}^{-,-}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) & \mathbf{P}^{+,-}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) & \mathbf{P}^{+,-}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) & \mathbf{P}^{+,-}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \end{bmatrix} \hat{\Gamma}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right), \quad (9)$$

方程(2)有解, 当且仅当式(9)有解。

设

$$\Gamma(x, y) = \sum_{k,l} \begin{bmatrix} \mathbf{P}_{k,l}^{+,+} & \mathbf{P}_{k,l}^{+,-} & \mathbf{P}_{k,l}^{-,+} & \mathbf{P}_{k,l}^{-,-} \\ \mathbf{P}_{k,-l}^{+,-} & \mathbf{P}_{k,-l}^{+,+} & \mathbf{P}_{k,-l}^{-,-} & \mathbf{P}_{k,-l}^{-,+} \\ \mathbf{P}_{-k,l}^{-,+} & \mathbf{P}_{-k,l}^{-,-} & \mathbf{P}_{-k,l}^{+,+} & \mathbf{P}_{-k,l}^{+,-} \\ \mathbf{P}_{-k,-l}^{-,-} & \mathbf{P}_{-k,-l}^{+,-} & \mathbf{P}_{-k,-l}^{+,-} & \mathbf{P}_{-k,-l}^{+,-} \end{bmatrix} \Gamma(ax - k, ay - l), \quad (10)$$

则(9)式为 $\Gamma(x, y)$ 在频域里的 a 尺度加密方程, 它的加细面具符号为

$$\mathbf{P}(\omega_1, \omega_2) = \begin{bmatrix} \mathbf{P}^{+,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) & \mathbf{P}^{+,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) & \mathbf{P}^{-,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) & \mathbf{P}^{-,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \\ \mathbf{P}^{+,-}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) & \mathbf{P}^{+,+}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) & \mathbf{P}^{-,-}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) & \mathbf{P}^{-,+}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \\ \mathbf{P}^{-,+}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) & \mathbf{P}^{-,-}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) & \mathbf{P}^{+,+}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) & \mathbf{P}^{+,-}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \\ \mathbf{P}^{-,-}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) & \mathbf{P}^{+,-}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) & \mathbf{P}^{+,-}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) & \mathbf{P}^{+,-}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \end{bmatrix} \quad (11)$$

定义方程(1)的自相关矩阵符号

$$\Omega(x, y) = \sum_{k,l} \begin{bmatrix} \Omega_{11} & \Omega_{12} & \Omega_{13} & \Omega_{14} \\ \Omega_{21} & \Omega_{22} & \Omega_{23} & \Omega_{24} \\ \Omega_{31} & \Omega_{32} & \Omega_{33} & \Omega_{34} \\ \Omega_{41} & \Omega_{42} & \Omega_{43} & \Omega_{44} \end{bmatrix} e^{-i\left(\frac{\omega_1 k + \omega_2 l}{a}\right)},$$

其中

$$\begin{aligned} \Omega_{11} &= \langle \Phi(x, y), \Phi(x - k, y - l) \rangle; \Omega_{12} = \langle \Phi(x, y), \Phi(x - k, l - y) \rangle; \\ \Omega_{13} &= \langle \Phi(x, y), \Phi(k - x, y - l) \rangle; \Omega_{14} = \langle \Phi(x, y), \Phi(k - x, l - y) \rangle; \\ \Omega_{21} &= \langle \Phi(x, -y), \Phi(x - k, y - l) \rangle; \Omega_{22} = \langle \Phi(x, -y), \Phi(x - k, l - y) \rangle; \\ \Omega_{23} &= \langle \Phi(x, -y), \Phi(k - x, y - l) \rangle; \Omega_{24} = \langle \Phi(x, -y), \Phi(k - x, l - y) \rangle; \\ \Omega_{31} &= \langle \Phi(-x, y), \Phi(x - k, y - l) \rangle; \Omega_{32} = \langle \Phi(-x, y), \Phi(x - k, l - y) \rangle; \\ \Omega_{33} &= \langle \Phi(-x, y), \Phi(k - x, y - l) \rangle; \Omega_{34} = \langle \Phi(-x, y), \Phi(k - x, l - y) \rangle; \\ \Omega_{41} &= \langle \Phi(-x, -y), \Phi(x - k, y - l) \rangle; \Omega_{42} = \langle \Phi(-x, -y), \Phi(x - k, l - y) \rangle; \end{aligned}$$

$$\Omega_{43} = \langle \Phi(-x, -y), \Phi(k-x, y-l) \rangle; \Omega_{44} = \langle \Phi(-x, -y), \Phi(k-x, l-y) \rangle.$$

下面引入变换算子 τ :

$$\tau A((\omega_1)^a, (\omega_2)^a) = \sum_{k,l=0}^{a-1} P\left(\omega_1 + \frac{2k\pi}{a}, \omega_2 + \frac{2l\pi}{a}\right) A\left(\omega_1 + \frac{2k\pi}{a}, \omega_2 + \frac{2l\pi}{a}\right) P^*\left(\omega_1 + \frac{2k\pi}{a}, \omega_2 + \frac{2l\pi}{a}\right), \quad (12)$$

其中 $A((\omega_1)^a, (\omega_2)^a)$ 是 $P(\omega_1, \omega_2)$ 的 Laurent 多项式, $P(\omega_1, \omega_2)$ 由(12)式可知。

关于 $\Omega(\omega_1, \omega_2)$ 和 τ 可以有下面的引理。

引理 1: 矩阵符号 $\Omega(\omega_1, \omega_2)$ 和变换算子 τ 的定义如上, 那么由 Poisson 求和公式可得

$$\Omega(\omega_1, \omega_2) = \sum_{k,l} \begin{bmatrix} \Phi\left(\omega_1 + \frac{2k\pi}{a}, \omega_2 + \frac{2l\pi}{a}\right) \\ \Phi\left(\omega_1 + \frac{2k\pi}{a}, -\omega_2 - \frac{2l\pi}{a}\right) \\ \Phi\left(-\omega_1 - \frac{2k\pi}{a}, \omega_2 + \frac{2l\pi}{a}\right) \\ \Phi\left(-\omega_1 - \frac{2k\pi}{a}, -\omega_2 - \frac{2l\pi}{a}\right) \end{bmatrix} \begin{bmatrix} \Phi\left(\omega_1 + \frac{2k\pi}{a}, \omega_2 + \frac{2l\pi}{a}\right) \\ \Phi\left(\omega_1 + \frac{2k\pi}{a}, -\omega_2 - \frac{2l\pi}{a}\right) \\ \Phi\left(-\omega_1 - \frac{2k\pi}{a}, \omega_2 + \frac{2l\pi}{a}\right) \\ \Phi\left(-\omega_1 - \frac{2k\pi}{a}, -\omega_2 - \frac{2l\pi}{a}\right) \end{bmatrix}^T$$

进一步, 我们可以得出 $\Omega(\omega_1, \omega_2)$ 是 τ 相应于特征值为 1 的特征矩阵。

定理 1: 加细方程(1)有紧支撑解当且仅当它的面具符号满足下面情况之一

$$1) \quad \begin{cases} \sum_{k,l} (P_{k,l}^{+,+} + P_{k,l}^{+,-} + P_{k,l}^{-,+} + P_{k,l}^{-,-}) = a^2 I, \\ \left| \sum_{k,l} (P_{k,l}^{+,+} - P_{k,l}^{+,-} - P_{k,l}^{-,+} + P_{k,l}^{-,-}) \right| \leq a^2, \\ \left| \sum_{k,l} (P_{k,l}^{+,+} + P_{k,l}^{+,-} - P_{k,l}^{-,+} - P_{k,l}^{-,-}) \right| \leq a^2, \\ \left| \sum_{k,l} (P_{k,l}^{+,+} - P_{k,l}^{+,-} + P_{k,l}^{-,+} - P_{k,l}^{-,-}) \right| \leq a^2; \end{cases}$$

$$2) \quad \begin{cases} \left| \sum_{k,l} (P_{k,l}^{+,+} + P_{k,l}^{+,-} + P_{k,l}^{-,+} + P_{k,l}^{-,-}) \right| \leq a^2, \\ \sum_{k,l} (P_{k,l}^{+,+} - P_{k,l}^{+,-} - P_{k,l}^{-,+} + P_{k,l}^{-,-}) = a^2 I, \\ \left| \sum_{k,l} (P_{k,l}^{+,+} + P_{k,l}^{+,-} - P_{k,l}^{-,+} - P_{k,l}^{-,-}) \right| \leq a^2, \\ \left| \sum_{k,l} (P_{k,l}^{+,+} - P_{k,l}^{+,-} + P_{k,l}^{-,+} - P_{k,l}^{-,-}) \right| \leq a^2; \end{cases}$$

$$3) \quad \begin{cases} \left| \sum_{k,l} (P_{k,l}^{+,+} + P_{k,l}^{+,-} + P_{k,l}^{-,+} + P_{k,l}^{-,-}) \right| \leq a^2, \\ \left| \sum_{k,l} (P_{k,l}^{+,+} - P_{k,l}^{+,-} - P_{k,l}^{-,+} + P_{k,l}^{-,-}) \right| \leq a^2, \\ \sum_{k,l} (P_{k,l}^{+,+} + P_{k,l}^{+,-} - P_{k,l}^{-,+} - P_{k,l}^{-,-}) = a^2 I, \\ \left| \sum_{k,l} (P_{k,l}^{+,+} - P_{k,l}^{+,-} + P_{k,l}^{-,+} - P_{k,l}^{-,-}) \right| \leq a^2; \end{cases}$$

$$4) \quad \begin{cases} \left| \sum_{k,l} (\mathbf{P}_{k,l}^{+,+} + \mathbf{P}_{k,l}^{+,-} + \mathbf{P}_{k,l}^{-,+} + \mathbf{P}_{k,l}^{-,-}) \right| \leq a^2, \\ \left| \sum_{k,l} (\mathbf{P}_{k,l}^{+,+} - \mathbf{P}_{k,l}^{+,-} - \mathbf{P}_{k,l}^{-,+} + \mathbf{P}_{k,l}^{-,-}) \right| \leq a^2, \\ \left| \sum_{k,l} (\mathbf{P}_{k,l}^{+,+} + \mathbf{P}_{k,l}^{+,-} - \mathbf{P}_{k,l}^{-,+} - \mathbf{P}_{k,l}^{-,-}) \right| \leq a^2, \\ \sum_{k,l} (\mathbf{P}_{k,l}^{+,+} - \mathbf{P}_{k,l}^{+,-} + \mathbf{P}_{k,l}^{-,+} - \mathbf{P}_{k,l}^{-,-}) = a^2 \mathbf{I}; \end{cases}$$

证明: 根据文献[5] [6] [7] [8], 方程(10)存在紧支撑分布解当且仅当 1 是(11)式定义矩阵 $\mathbf{P}(1,1)$ 的一个特征值, $\mathbf{P}(1,1)$ 的其他特征值的模都不大于 1。另外, $\mathbf{P}(1,1)$ 的 4 个特征值分别是

$$\frac{1}{a^2} \sum_{k,l} (\mathbf{P}_{k,l}^{+,+} + \mathbf{P}_{k,l}^{+,-} + \mathbf{P}_{k,l}^{-,+} + \mathbf{P}_{k,l}^{-,-}), \quad \frac{1}{a^2} \sum_{k,l} (\mathbf{P}_{k,l}^{+,+} - \mathbf{P}_{k,l}^{+,-} - \mathbf{P}_{k,l}^{-,+} + \mathbf{P}_{k,l}^{-,-}), \quad \frac{1}{a^2} \sum_{k,l} (\mathbf{P}_{k,l}^{+,+} + \mathbf{P}_{k,l}^{+,-} - \mathbf{P}_{k,l}^{-,+} - \mathbf{P}_{k,l}^{-,-}) \text{ 以及} \\ \frac{1}{a^2} \sum_{k,l} (\mathbf{P}_{k,l}^{+,+} - \mathbf{P}_{k,l}^{+,-} + \mathbf{P}_{k,l}^{-,+} - \mathbf{P}_{k,l}^{-,-}) \text{。定理易证。}$$

定理 2: 若要 $\Phi(x, y)$ 有紧支撑性, 则要证明每个分量是紧支撑的。设 $\Phi(x) = [\varphi_1(x), \varphi_2(x), \dots, \varphi_r(x)]^\top$, 其中 $\varphi_i(x)$ 和 $\varphi(y)$ 是双向细分函数满足

$$\varphi_i(x) = \sum_{k=0}^{N_1} \mathbf{P}_k^+ \varphi_i(ax - k) + \sum_{k=-N_1}^0 \mathbf{P}_k^- \varphi_i(k - ax) \\ \varphi(y) = \sum_{k=0}^{N_2} p_k^+ \varphi(ay - k) + \sum_{k=-N_2}^0 p_k^- \varphi(k - ay)$$

如果 $\Phi(x)$ 和 $\varphi(y)$ 是紧支撑的, 那么可根据 $\Phi(x)$ 和 $\varphi(y)$ 的张量积生成二维四向加细函数

$$Supp \Phi(x) \subseteq \left[-\frac{N_1}{a-1}, \frac{N_1}{a-1} \right], \quad Supp \varphi(y) \subseteq \left[-\frac{N_2}{a-1}, \frac{N_2}{a-1} \right], \text{ 则有}$$

$$Supp \Phi(x, y) = \Phi(x) \cdot \varphi(y) \subseteq \left[-\frac{N_1}{a-1}, \frac{N_1}{a-1} \right] \times \left[-\frac{N_2}{a-1}, \frac{N_2}{a-1} \right]$$

证明: 根据文献[9]中定理 4 可知。

3. a 尺度二维四向多分辨分析

$$\text{定义子空间序列 } \{V_j\}_{j \in \mathbb{Z}} \subset L^2(\mathbf{R}^2), \\ V_j = Close_{L^2(\mathbf{R}^2)} \langle a^j \Phi(a^j x - k, a^j y - l), a^j \Phi(a^j x - k, l - a^j y), \\ a^j \Phi(k - a^j x, a^j y - l), a^j \Phi(k - a^j x, l - a^j y), k, l \in \mathbb{Z} \rangle, \quad (13)$$

那么要产生在 $L^2(\mathbf{R}^2)$ 中的一个多分辨分析 $\{V_j\}_{j \in \mathbb{Z}}$ 当且仅当(13)式里的 V_j 应当满足以下条件:

1) $\cdots \subset V_{-1} \subset V_0 \subset V_1 \subset \cdots$;

2) $Close_{L^2(\mathbf{R}^2)} \bigcup_{j \in \mathbb{Z}} V_j = L^2(\mathbf{R}^2)$;

3) $\bigcap_{j \in \mathbb{Z}} V_j = \{0\}$;

4) $f(x, y) \in V_j \Leftrightarrow f(ax, ay) \in V_{j+1}$;

5) 存在 $L^2(\mathbf{R}^2)$ 里的一个函数 $\Phi(x, y)$, 使得集合

$\{\Phi(x - k, y - l), \Phi(x - k, l - y), \Phi(k - x, y - l), \Phi(k - x, l - y) : k, l \in \mathbb{Z}\}$ 是 V_0 的 Riesz 基, 那么就有两个常数

$0 < A \leq B < \infty$ ，则对于系数向量序列

$$\left\{c_{k,l}^{k,l}\right\}_{k,l \in \mathbf{Z}} = \left\{\left[c_1^{k,l}, c_2^{k,l}, c_3^{k,l}, c_4^{k,l}\right]\right\}_{k,l \in \mathbf{Z}} \subset l^2(\mathbf{Z}^4) \text{ 有}$$

$$\begin{aligned} A \left\| \sum_{k,l \in \mathbf{Z}} c_{k,l} c_{k,l}^* \right\|_2^2 &\leq \left\| \sum_{k,l \in \mathbf{Z}} c_1^{k,l} \Phi(x-k, y-l) + \sum_{k,l \in \mathbf{Z}} c_2^{k,l} \Phi(x-k, l-y) + \sum_{k,l \in \mathbf{Z}} c_3^{k,l} \Phi(k-x, y-l) + \sum_{k,l \in \mathbf{Z}} c_4^{k,l} \Phi(k-x, l-y) \right\|_2^2 \\ &\leq B \left\| \sum_{k,l \in \mathbf{Z}} c_{k,l} c_{k,l}^* \right\|_2^2, \end{aligned} \quad (14)$$

称式(14)为稳定性条件。

根据多重多分辨分析的性质 $f(x, y) \in V_j \Leftrightarrow f\left(x + \frac{k}{a^j}, y + \frac{l}{a^j}\right) \in V_j$ ，可以定义：

$$\Phi_{j,k,l}^{+,+} = a^j \Phi(a^j x - k, a^j y - l), \quad \Phi_{j,k,l}^{+,-} = a^j \Phi(a^j x - k, l - a^j y),$$

$$\Phi_{j,k,l}^{-,+} = a^j \Phi(k - a^j x, a^j y - l), \quad \Phi_{j,k,l}^{-,-} = a^j \Phi(k - a^j x, l - a^j y).$$

则 $\{\Phi_{j,k,l}^{+,+}, \Phi_{j,k,l}^{+,-}, \Phi_{j,k,l}^{-,+}, \Phi_{j,k,l}^{-,-} : k, l \in \mathbf{Z}\}$ 同样可以构成 V_j 的 Riesz 基，有

$$A \left\| \sum_{k,l \in \mathbf{Z}} c_{k,l} c_{k,l}^* \right\|_2^2 \leq \left\| \sum_{k,l \in \mathbf{Z}} c_1^{k,l} \Phi_{j,k,l}^{+,+} + \sum_{k,l \in \mathbf{Z}} c_2^{k,l} \Phi_{j,k,l}^{+,-} + \sum_{k,l \in \mathbf{Z}} c_3^{k,l} \Phi_{j,k,l}^{-,+} + \sum_{k,l \in \mathbf{Z}} c_4^{k,l} \Phi_{j,k,l}^{-,-} \right\|_2^2 \leq B \left\| \sum_{k,l \in \mathbf{Z}} c_{k,l} c_{k,l}^* \right\|_2^2,$$

因为 $\Phi(x, y) \in V_0 \subset V_1$ ，并且 $\{\Phi_{j,k,l}^{+,+}, \Phi_{j,k,l}^{+,-}, \Phi_{j,k,l}^{-,+}, \Phi_{j,k,l}^{-,-} : k, l \in \mathbf{Z}\}$ 同样也可以构成 V_1 的 Riesz 基，故有 $c_1^{k,l}, c_2^{k,l}, c_3^{k,l}, c_4^{k,l} \in l^2(\mathbf{Z}^4)$ ，从而使 $\Phi(x, y)$ 满足(1)式。

定理 3：如果尺度函数 $\Phi(x, y) \in L^2(\mathbf{R}^2)$ 符合多分辨分析，现定义 $V_j = \{\Phi_{j,k,l}^{+,+}, \Phi_{j,k,l}^{+,-}, \Phi_{j,k,l}^{-,+}, \Phi_{j,k,l}^{-,-} : k, l \in \mathbf{Z}\}$ 构成 V_0 的 Riesz 基。若存在函数集 $\{\Phi(x-k, y-l), \Phi(x-k, l-y), \Phi(k-x, y-l), \Phi(k-x, l-y) : k, l \in \mathbf{Z}\}$ 构成 V_0 的 Riesz 基，那么 $\bigcap_{j \in \mathbf{Z}} V_j = \{0\}$ 。

证明：由于 $\{\Phi_{j,k,l}^{+,+}, \Phi_{j,k,l}^{+,-}, \Phi_{j,k,l}^{-,+}, \Phi_{j,k,l}^{-,-} : k, l \in \mathbf{Z}\}$ 构成 V_0 的 Riesz 基，故存在两个常数 $0 < A \leq B < \infty$ ，对任意的 $f(x, y) \in V_0$ ，有

$$A \|f\|_2^2 \leq \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{0,k,l}^{+,+} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{0,k,l}^{+,-} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{0,k,l}^{-,+} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{0,k,l}^{-,-} \rangle|^2 \leq B \|f\|_2^2,$$

所以对于所有的 $f(x, y) \in V_j$ ，就有

$$A \|f\|_2^2 \leq \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{j,k,l}^{+,+} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{j,k,l}^{+,-} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{j,k,l}^{-,+} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{j,k,l}^{-,-} \rangle|^2 \leq B \|f\|_2^2,$$

对于 $\forall \varepsilon > 0$ ， $f(x, y) \in \bigcap_{j \in \mathbf{Z}} V_j$ ，存在一个紧支撑连续函数 $\tilde{f}(x, y)$ ，使 $\|f - \tilde{f}\|_2 \leq \varepsilon$ 。

若 P_j 是 V_j 的正交投影算子，则 $\|f - P_j \tilde{f}\| \leq \|f - P_j \tilde{f}\| = \|P_j f - P_j \tilde{f}\| \leq \|f - \tilde{f}\| \leq \varepsilon$ ，故 $\|f\| \leq \varepsilon + \|P_j \tilde{f}\|, \forall j \in \mathbf{Z}$ 。

设 $\text{Supp } f(x, y) = [-r, r] \times [-r, r] = S$ ，则

$$\begin{aligned} \sum_{k,l \in \mathbf{Z}} |\langle \tilde{f}, \Phi_{j,k,l}^{+,+} \rangle|^2 &\leq a^{2j} \sum_{k,l \in \mathbf{Z}} \left[\int_{(x,y) \in S} |\tilde{f}(x, y)| |\Phi(a^j x - k, a^j y - l)| dx dy \right]^2 \\ &\leq a^{2j} \|\tilde{f}(x, y)\|_{L^\infty}^2 \sum_{k,l \in \mathbf{Z}} \left[\int_{(x,y) \in S} |\Phi(a^j x - k, a^j y - l)| dx dy \right]^2 \\ &\leq a^{2j} \|\tilde{f}(x, y)\|_{L^\infty}^2 \sum_{k,l \in \mathbf{Z}} \int_{(x,y) \in S} |\Phi(a^j x - k, a^j y - l)|^2 dx dy \\ &= \|\tilde{f}(x, y)\|_{L^\infty}^2 \int_{D^j} |\Phi(x, y)|^2 dx dy \end{aligned}$$

其中 $D^j = \bigcup_{k,l} [k - a^j r, k + a^j r] \times [l - a^j r, l + a^j r]$ 。所以, 当 $j \rightarrow -\infty$ 时 $\sum_{k,l \in \mathbf{Z}} |\langle \tilde{f}, \Phi_{j,k,l}^{+,+} \rangle|^2 \rightarrow 0$ 。同理, 可以证

明: $\sum_{k,l \in \mathbf{Z}} |\langle \tilde{f}, \Phi_{j,k,l}^{-,+} \rangle|^2 \rightarrow 0$, $\sum_{k,l \in \mathbf{Z}} |\langle \tilde{f}, \Phi_{j,k,l}^{+,-} \rangle|^2 \rightarrow 0$, $\sum_{k,l \in \mathbf{Z}} |\langle \tilde{f}, \Phi_{j,k,l}^{-,-} \rangle|^2 \rightarrow 0$ 。又由于

$$\|P_j \tilde{f}\|^2 \leq \frac{1}{A} \sum_{k,l \in \mathbf{Z}} \left[|\langle f, \Phi_{0,k,l}^{+,+} \rangle|^2 + |\langle f, \Phi_{0,k,l}^{+,-} \rangle|^2 + |\langle f, \Phi_{0,k,l}^{-,+} \rangle|^2 + |\langle f, \Phi_{0,k,l}^{-,-} \rangle|^2 \right]$$

所以 $\lim_{j \rightarrow -\infty} \|P_j \tilde{f}\| = 0$ 。根据 $\|f\| \leq \varepsilon + \|P_j \tilde{f}\|, \forall j \in \mathbf{Z}$, 可以知道 $f(x, y) = 0$ 。

定理 4: 若 $\Phi(x, y) \in L^2(\mathbf{R}^2)$ 符合定义式(1), 根据(13)式定义的 V_j , 若 $\Phi(x, y)$ 满足 1) 集合 $\{\Phi(x-k, y-l), \Phi(x-k, l-y), \Phi(k-x, y-l), \Phi(k-x, l-y) : k, l \in \mathbf{Z}\}$ 是 V_0 的 Riesz 基; 2) 对所有的 $(\omega_1, \omega_2) \in \mathbf{R}^2$, $\hat{\Phi}(\omega_1, \omega_2)$ 有界; 3) $\hat{\Phi}(\omega_1, \omega_2)$ 在 $(\omega_1, \omega_2) = (0, 0)$ 附近连续, $\hat{\Phi}(\omega_1, \omega_2) \neq 0$, 那么 $\text{Close}_{L^2(\mathbf{R}^2)} \bigcup_{j \in \mathbf{Z}} V_j = L^2(\mathbf{R}^2)$ 。

证明: 由于 $\{\Phi_{j,k,l}^{+,+}, \Phi_{j,k,l}^{+,-}, \Phi_{j,k,l}^{-,+}, \Phi_{j,k,l}^{-,-} : k, l \in \mathbf{Z}\}$ 构成 V_0 的 Riesz 基, 故存在两个常数 $0 < A \leq B < \infty$, 对任意的 $f(x, y) \in V_0$, 有

$$A \|f\|_2^2 \leq \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{0,k,l}^{+,+} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{0,k,l}^{+,-} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{0,k,l}^{-,+} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{0,k,l}^{-,-} \rangle|^2 \leq B \|f\|_2^2,$$

所以对于所有的 $f(x, y) \in V_j$, 就有

$$A \|f\|_2^2 \leq \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{j,k,l}^{+,+} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{j,k,l}^{+,-} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{j,k,l}^{-,+} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle f, \Phi_{j,k,l}^{-,-} \rangle|^2 \leq B \|f\|_2^2,$$

对于 $\forall \varepsilon > 0$, $f(x, y) \in (\bigcup_{j \in \mathbf{Z}} V_j)^\perp$, 那么就有紧支撑连续函数 $\tilde{f}(x, y)$, 使 $\|f - \tilde{f}\|_{L^2} \leq \varepsilon$ 。

若 P_j 是 V_j 的正交投影算子, 则 $\|P_j \tilde{f}\| = \|P_j(\tilde{f} - f)\|_{L^2} \leq \varepsilon$ 。又因为 $P_j \tilde{f} \in V_j$, 则

$$B \|P_j \tilde{f}\|^2 \geq \sum_{k,l \in \mathbf{Z}} |\langle P_j \tilde{f}, \Phi_{j,k,l}^{+,+} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle P_j \tilde{f}, \Phi_{j,k,l}^{+,-} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle P_j \tilde{f}, \Phi_{j,k,l}^{-,+} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle P_j \tilde{f}, \Phi_{j,k,l}^{-,-} \rangle|^2,$$

进一步可以得到

$$\begin{aligned} & \sum_{k,l \in \mathbf{Z}} |\langle P_j \tilde{f}, \Phi_{j,k,l}^{+,+} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle P_j \tilde{f}, \Phi_{j,k,l}^{+,-} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle P_j \tilde{f}, \Phi_{j,k,l}^{-,+} \rangle|^2 + \sum_{k,l \in \mathbf{Z}} |\langle P_j \tilde{f}, \Phi_{j,k,l}^{-,-} \rangle|^2 \\ &= \frac{1}{(2\pi)^4} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \left(|\hat{\Phi}(a^{-j} \omega_1, a^{-j} \omega_2)|^2 + |\hat{\Phi}(a^{-j} \omega_1, -a^{-j} \omega_2)|^2 + |\hat{\Phi}(-a^{-j} \omega_1, a^{-j} \omega_2)|^2 \right. \\ & \quad \left. + |\hat{\Phi}(-a^{-j} \omega_1, -a^{-j} \omega_2)|^2 \right) \widehat{P_j \tilde{f}}(\omega_1, \omega_2) d\omega_1 d\omega_2 + D \end{aligned}$$

其中

$$D \leq \left(\|\hat{\Phi}(\omega_1, \omega_2)\|_{L^\infty}^2 + \|\hat{\Phi}(\omega_1, -\omega_2)\|_{L^\infty}^2 + \|\hat{\Phi}(-\omega_1, \omega_2)\|_{L^\infty}^2 + \|\hat{\Phi}(-\omega_1, -\omega_2)\|_{L^\infty}^2 \right) \cdot \sum_{k \neq 0, l \neq 0} |P_j \tilde{f}(a^j k, a^j l)|^2.$$

因为 $\tilde{f}(x, y) \in C^\infty$, 所以存在一个常数 M , 使 $|\tilde{f}(x, y)| \leq M(1 + |x + y|)^{-2}$ 故

$$\begin{aligned} D &\leq M^2 \left(\|\hat{\Phi}(\omega_1, \omega_2)\|_{L^\infty}^2 + \|\hat{\Phi}(\omega_1, -\omega_2)\|_{L^\infty}^2 + \|\hat{\Phi}(-\omega_1, \omega_2)\|_{L^\infty}^2 + \|\hat{\Phi}(-\omega_1, -\omega_2)\|_{L^\infty}^2 \right) \cdot \sum_{k \neq 0, l \neq 0} |P_j \tilde{f}(a^j k, a^j l)|^2 \\ &\leq M^2 \left(\|\hat{\Phi}(\omega_1, \omega_2)\|_{L^\infty}^2 + \|\hat{\Phi}(\omega_1, -\omega_2)\|_{L^\infty}^2 + \|\hat{\Phi}(-\omega_1, \omega_2)\|_{L^\infty}^2 + \|\hat{\Phi}(-\omega_1, -\omega_2)\|_{L^\infty}^2 \right) \cdot \sum_{k \neq 0, l \neq 0} (1 + |a^j k + a^j l|)^{-2} \\ &\leq M'^2 a^{-2j} \end{aligned}$$

由以上的推导, 可以得到

$$\begin{aligned}
& \frac{1}{(2\pi)^4} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \left(|\hat{\Phi}(a^{-j}\omega_1, a^{-j}\omega_2)|^2 + |\hat{\Phi}(a^{-j}\omega_1, -a^{-j}\omega_2)|^2 + |\hat{\Phi}(-a^{-j}\omega_1, a^{-j}\omega_2)|^2 \right. \\
& \quad \left. + |\hat{\Phi}(-a^{-j}\omega_1, -a^{-j}\omega_2)|^2 \right) \widehat{P_j f}(\omega_1, \omega_2) d\omega_1 d\omega_2 \leq \sum_{k,l \in \mathbf{Z}} \left| \langle P_j \tilde{f}, \Phi_{j,k,l}^{+,+} \rangle \right|^2 \\
& \quad + \sum_{k,l \in \mathbf{Z}} \left| \langle P_j \tilde{f}, \Phi_{j,k,l}^{+,-} \rangle \right|^2 + \sum_{k,l \in \mathbf{Z}} \left| \langle P_j \tilde{f}, \Phi_{j,k,l}^{-,+} \rangle \right|^2 + \sum_{k,l \in \mathbf{Z}} \left| \langle P_j \tilde{f}, \Phi_{j,k,l}^{-,-} \rangle \right|^2 + |D| \\
& \leq B\varepsilon^2 + M'^2 a^{-2j}.
\end{aligned}$$

由于 $\Phi(\omega_1, \omega_2)$ 有界且在 $(\omega_1, \omega_2) = (0, 0)$ 附近处连续且 $\Phi(0, 0) \neq 0$ ，故当 $j \rightarrow +\infty$ 时，以上不等式收敛于

$$\begin{aligned}
& \frac{1}{(2\pi)^4} \left(|\hat{\Phi}(0,0)|^2 + |\hat{\Phi}(0,0)|^2 + |\hat{\Phi}(0,0)|^2 + |\hat{\Phi}(0,0)|^2 \right) \cdot \left\| \widehat{P_j f} \right\|_{L^2}^2 = \frac{1}{4\pi^4} |\hat{\Phi}(0,0)|^2 \cdot \left\| \widehat{P_j f} \right\|_{L^2}^2 \\
& \text{从而 } \left\| \widehat{P_j f} \right\|_{L^2}^2 \leq \frac{(2\pi)^4 B\varepsilon^2}{4|\hat{\Phi}(0,0)|^2} = \frac{4\pi^4 B\varepsilon^2}{|\hat{\Phi}(0,0)|^2}, \text{ 所以 } \|f\|_{L^2} \leq \varepsilon + \left\| \widehat{P_j f} \right\|_{L^2} \leq \varepsilon + \frac{2\pi^2 \sqrt{B\varepsilon}}{\sqrt{|\hat{\Phi}(0,0)|^2}}, \text{ 因为 } \varepsilon \text{ 是任意小的,}
\end{aligned}$$

所以 $f = 0$ ，则说明 $\text{Close}_{L^2(\mathbf{R}^2)} \bigcup_{j \in \mathbf{Z}} V_j = L^2(\mathbf{R}^2)$ 。

4. 双正交二维四向加细函数和小波

定理 5：如果二维四向加细函数是正交的，那么应该满足下列等式

$$\begin{aligned}
\langle \Phi(x, y), \Phi(x-k, y-l) \rangle &= \delta_{0,k} \delta_{0,l} \mathbf{I}_r, \quad \langle \Phi(x, y), \Phi(k-x, y-l) \rangle = \mathbf{O}_r, \\
\langle \Phi(x, y), \Phi(x-k, l-y) \rangle &= \mathbf{O}_r, \quad \langle \Phi(x, y), \Phi(k-x, l-y) \rangle = \mathbf{O}_r.
\end{aligned}$$

定理 6：如果二维四向加细函数 $\Phi(x, y)$ 和 $\tilde{\Phi}(x, y)$ 是双正交的，那么应该满足下列等式

$$\begin{aligned}
\langle \Phi(x, y), \tilde{\Phi}(x-k, y-l) \rangle &= \delta_{0,k} \delta_{0,l} \mathbf{I}_r, \quad \langle \Phi(x, y), \tilde{\Phi}(k-x, y-l) \rangle = \mathbf{O}_r, \\
\langle \Phi(x, y), \tilde{\Phi}(x-k, l-y) \rangle &= \mathbf{O}_r, \quad \langle \Phi(x, y), \tilde{\Phi}(k-x, l-y) \rangle = \mathbf{O}_r.
\end{aligned}$$

定理 7：如果二维四向加细函数 $\Phi(x, y)$ 和 $\tilde{\Phi}(x, y)$ 是双正交的尺度函数，那么它的双正面具，正负面具和双负面具符号都应该满足

$$\left\{
\begin{aligned}
& \sum_{k,l=0}^{a-1} \left\{ \mathbf{P}^{+,+}(p_1, p_2) \tilde{\mathbf{P}}^{+,+}(-p_1, -p_2) + \mathbf{P}^{-,+}(p_1, p_2) \tilde{\mathbf{P}}^{-,+}(-p_1, -p_2) \right. \\
& \quad \left. + \mathbf{P}^{+,-}(p_1, p_2) \tilde{\mathbf{P}}^{+,-}(-p_1, -p_2) + \mathbf{P}^{-,-}(p_1, p_2) \tilde{\mathbf{P}}^{-,-}(-p_1, -p_2) \right\} = \mathbf{I}_r \\
& \sum_{k,l=0}^{a-1} \left\{ \mathbf{P}^{+,+}(p_1, p_2) \tilde{\mathbf{P}}^{+,-}(-p_1, p_2) + \mathbf{P}^{+,-}(p_1, p_2) \tilde{\mathbf{P}}^{+,-}(-p_1, p_2) \right. \\
& \quad \left. + \mathbf{P}^{-,+}(p_1, p_2) \tilde{\mathbf{P}}^{-,-}(p_1, p_2) + \mathbf{P}^{-,-}(p_1, p_2) \tilde{\mathbf{P}}^{-,+}(p_1, p_2) \right\} = \mathbf{O}_r \\
& \sum_{k,l=0}^{a-1} \left\{ \mathbf{P}^{+,+}(p_1, p_2) \tilde{\mathbf{P}}^{-,+}(p_1, -p_2) + \mathbf{P}^{+,-}(p_1, p_2) \tilde{\mathbf{P}}^{-,-}(p_1, -p_2) \right. \\
& \quad \left. + \mathbf{P}^{-,+}(p_1, p_2) \tilde{\mathbf{P}}^{+,-}(p_1, -p_2) + \mathbf{P}^{-,-}(p_1, p_2) \tilde{\mathbf{P}}^{+,-}(p_1, -p_2) \right\} = \mathbf{O}_r \\
& \sum_{k,l=0}^{a-1} \left\{ \mathbf{P}^{+,+}(p_1, p_2) \tilde{\mathbf{P}}^{-,-}(p_1, p_2) + \mathbf{P}^{+,-}(p_1, p_2) \tilde{\mathbf{P}}^{-,+}(p_1, p_2) \right. \\
& \quad \left. + \mathbf{P}^{-,+}(p_1, p_2) \tilde{\mathbf{P}}^{+,-}(p_1, p_2) + \mathbf{P}^{-,-}(p_1, p_2) \tilde{\mathbf{P}}^{+,-}(p_1, p_2) \right\} = \mathbf{O}_r
\end{aligned} \right. \tag{15}$$

其中: $p_1 = \omega_1 + \frac{2k\pi}{a}$; $p_2 = \omega_2 + \frac{2l\pi}{a}$ 。

证明: 由文献[7]的定理1以及本文定理5定理6正交双正交定义易证。

假设 $\Phi(x, y)$ 和 $\tilde{\Phi}(x, y)$ 是双正交二维四向加细函数, 对任意的 $j \in \mathbf{Z}$, 定义 $V_{j+1} = V_j \oplus W_j$, 其中 W_j 是 V_j 在 V_{j+1} 中的正交补。那么当 $j \neq k$ 时, 就有 $W_j \perp W_k$ 并且 $L^2(R) = \bigoplus_{j \in \mathbf{Z}} W_j$, 其中

$$W_j = \bigoplus_{h=1}^{a-1} \left\{ W_j^{h,1} \oplus W_j^{h,2} \oplus W_j^{h,3} \right\}, \quad W_j^{h,1} \perp W_j^{h,2}, \quad W_j^{h,1} \perp W_j^{h,3}, \quad W_j^{h,2} \perp W_j^{h,3}.$$

如果有 r 个小波函数 $\psi_1(x), \psi_2(x), \dots, \psi_r(x)$, 则记 $\Psi^{h,i}(x) = [\psi_1(x), \psi_2(x), \dots, \psi_r(x)]^T$, 则通过张量积的构造就有

$$\Psi^{h,i}(x, y) = \Psi^{h,i}(x)\psi(y) = [\Psi_1(x, y), \Psi_2(x, y), \dots, \Psi_r(x, y)]^T$$

和

$$\tilde{\Psi}^{h,i}(x, y) = [\tilde{\Psi}_1(x, y), \tilde{\Psi}_2(x, y), \dots, \tilde{\Psi}_r(x, y)]^T$$

$(h=1, 2, \dots, a-1; i=1, 2, 3)$, 使得集合

$\{\Psi^{h,i}(x-k, y-l), \Psi^{h,i}(x-k, l-y), \Psi^{h,i}(k-x, y-l), \Psi^{h,i}(k-x, l-y); k, l \in \mathbf{Z}, h=1, 2, \dots, a-1; i=1, 2, 3\}$ 和集合 $\{\tilde{\Psi}^{h,i}(x-k, y-l), \tilde{\Psi}^{h,i}(x-k, l-y), \tilde{\Psi}^{h,i}(k-x, y-l), \tilde{\Psi}^{h,i}(k-x, l-y); k, l \in \mathbf{Z}, h=1, 2, \dots, a-1; i=1, 2, 3\}$ 构成 W_0 的一组双正交基, 则 $\Psi^{h,i}(x, y)$ 和 $\tilde{\Psi}^{h,i}(x, y)$ 是与 $\Phi(x, y)$ 和 $\tilde{\Phi}(x, y)$ 对应的双正交二维四向多小波函数, 应该满足

$$\begin{aligned} \langle \tilde{\Phi}(x, y), \Psi^{h,i}(x-k, y-l) \rangle &= \langle \tilde{\Phi}(x, y), \Psi^{h,i}(x-k, l-y) \rangle = \mathbf{O}_r, \\ \langle \Phi(x, y), \tilde{\Psi}^{h,i}(k-x, y-l) \rangle &= \langle \Phi(x, y), \tilde{\Psi}^{h,i}(k-x, l-y) \rangle = \mathbf{O}_r, \\ \langle \tilde{\Phi}(x, y), \Psi^{h,i}(k-x, y-l) \rangle &= \langle \tilde{\Phi}(x, y), \Psi^{h,i}(k-x, l-y) \rangle = \mathbf{O}_r, \\ \langle \Psi^{n,m}(x, y), \tilde{\Psi}^{s,t}(x-k, y-l) \rangle &= \delta_{n,s} \delta_{m,t} \delta_{0,k} \delta_{0,l} \mathbf{I}_r, \\ \langle \Psi^{n,m}(x, y), \tilde{\Psi}^{s,t}(x-k, l-y) \rangle &= \mathbf{O}_r, \\ \langle \tilde{\Psi}^{n,m}(x, y), \tilde{\Psi}^{s,t}(x-k, y-l) \rangle &= \delta_{n,s} \delta_{m,t} \delta_{0,k} \delta_{0,l} \mathbf{I}_r, \\ \langle \tilde{\Psi}^{n,m}(x, y), \tilde{\Psi}^{s,t}(x-k, l-y) \rangle &= \mathbf{O}_r, \\ \langle \Psi^{n,m}(x, y), \Psi^{s,t}(k-x, l-y) \rangle &= \mathbf{O}_r, \\ \langle \tilde{\Psi}^{n,m}(x, y), \Psi^{s,t}(k-x, y-l) \rangle &= \mathbf{O}_r, \\ \langle \tilde{\Psi}^{n,m}(x, y), \Psi^{s,t}(k-x, l-y) \rangle &= \mathbf{O}_r, \end{aligned} \tag{16}$$

其中: $h, n, s = 1, 2, \dots, a-1; i, m, t = 1, 2, 3$ 。

假如 $\Psi^{h,i}(x, y)$ 是 $\Phi(x, y)$ 对应的多小波函数, 相应的 $\tilde{\Psi}^{h,i}(x, y)$ 是 $\tilde{\Phi}(x, y)$ 对应的多小波函数, 那么就存在 $\{\mathcal{Q}_{k,l}^{h,i,+,+}\}_{k,l \in \mathbf{Z}}$, $\{\mathcal{Q}_{k,l}^{h,i,+,-}\}_{k,l \in \mathbf{Z}}$, $\{\mathcal{Q}_{k,l}^{h,i,-,+}\}_{k,l \in \mathbf{Z}}$, $\{\mathcal{Q}_{k,l}^{h,i,-,-}\}_{k,l \in \mathbf{Z}}$ 和 $\{\tilde{\mathcal{Q}}_{k,l}^{h,i,+,+}\}_{k,l \in \mathbf{Z}}$, $\{\tilde{\mathcal{Q}}_{k,l}^{h,i,+,-}\}_{k,l \in \mathbf{Z}}$, $\{\tilde{\mathcal{Q}}_{k,l}^{h,i,-,+}\}_{k,l \in \mathbf{Z}}$, $\{\tilde{\mathcal{Q}}_{k,l}^{h,i,-,-}\}_{k,l \in \mathbf{Z}}$, 满足

$$\begin{aligned} \Psi^{h,i}(x, y) &= \sum_{k,l} \mathcal{Q}_{k,l}^{h,i,+,+} \Phi(ax-k, ay-l) + \sum_{k,l} \mathcal{Q}_{k,l}^{h,i,+,-} \Phi(ax-k, l-ay) \\ &\quad + \sum_{k,l} \mathcal{Q}_{k,l}^{h,i,-,+} \Phi(k-ax, ay-l) + \sum_{k,l} \mathcal{Q}_{k,l}^{h,i,-,-} \Phi(k-ax, l-ay); \end{aligned} \tag{17}$$

$$\begin{aligned}\tilde{\Psi}^{h,i}(x,y) &= \sum_{k,l} \tilde{\mathbf{Q}}_{k,l}^{h,i,+,+} \tilde{\Phi}(ax-k, ay-l) + \sum_{k,l} \tilde{\mathbf{Q}}_{k,l}^{h,i,+,-} \tilde{\Phi}(ax-k, l-ay) \\ &\quad + \sum_{k,l} \tilde{\mathbf{Q}}_{k,l}^{h,i,-,+} \tilde{\Phi}(k-ax, ay-l) + \sum_{k,l} \tilde{\mathbf{Q}}_{k,l}^{h,i,-,-} \tilde{\Phi}(k-ax, l-ay).\end{aligned}\quad (18)$$

对(17)式和(18)式两边做 Fourier 变换

$$\begin{aligned}\hat{\Psi}^{h,i}(\omega_1, \omega_2) &= \mathbf{Q}^{h,i,+,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \hat{\Phi}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) + \mathbf{Q}^{h,i,+,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \hat{\Phi}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \\ &\quad + \mathbf{Q}^{h,i,-,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \hat{\Phi}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) + \mathbf{Q}^{h,i,-,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \hat{\Phi}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right); \\ \hat{\tilde{\Psi}}^{h,i}(\omega_1, \omega_2) &= \tilde{\mathbf{Q}}^{h,i,+,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \hat{\Phi}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) + \tilde{\mathbf{Q}}^{h,i,+,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \hat{\Phi}\left(\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right) \\ &\quad + \tilde{\mathbf{Q}}^{h,i,-,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \hat{\Phi}\left(-\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) + \tilde{\mathbf{Q}}^{h,i,-,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) \hat{\Phi}\left(-\frac{\omega_1}{a}, -\frac{\omega_2}{a}\right);\end{aligned}$$

其中

$$\begin{aligned}\mathbf{Q}^{h,i,+,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) &= \frac{1}{a^2} \sum_{k,l} \mathbf{Q}_{k,l}^{h,i,+,+} e^{-i\left(\frac{\omega_1 k}{a} + \frac{\omega_2 l}{a}\right)}, \mathbf{Q}^{h,i,+,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) = \frac{1}{a^2} \sum_{k,l} \mathbf{Q}_{k,l}^{h,i,+,-} e^{-i\left(\frac{\omega_1 k}{a} + \frac{\omega_2 l}{a}\right)}, \\ \mathbf{Q}^{h,i,-,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) &= \frac{1}{a^2} \sum_{k,l} \mathbf{Q}_{k,l}^{h,i,-,+} e^{-i\left(\frac{\omega_1 k}{a} + \frac{\omega_2 l}{a}\right)}, \mathbf{Q}^{h,i,-,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) = \frac{1}{a^2} \sum_{k,l} \mathbf{Q}_{k,l}^{h,i,-,-} e^{-i\left(\frac{\omega_1 k}{a} + \frac{\omega_2 l}{a}\right)},\end{aligned}$$

($h=1, 2, \dots, a-1; i=1, 2, 3$) 为 $\Psi^{h,i}(x, y)$ 的双正, 正负, 双负面具符号。

$$\begin{aligned}\tilde{\mathbf{Q}}^{h,i,+,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) &= \frac{1}{a^2} \sum_{k,l} \tilde{\mathbf{Q}}_{k,l}^{h,i,+,+} e^{-i\left(\frac{\omega_1 k}{a} + \frac{\omega_2 l}{a}\right)}, \tilde{\mathbf{Q}}^{h,i,+,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) = \frac{1}{a^2} \sum_{k,l} \tilde{\mathbf{Q}}_{k,l}^{h,i,+,-} e^{-i\left(\frac{\omega_1 k}{a} + \frac{\omega_2 l}{a}\right)}, \\ \tilde{\mathbf{Q}}^{h,i,-,+}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) &= \frac{1}{a^2} \sum_{k,l} \tilde{\mathbf{Q}}_{k,l}^{h,i,-,+} e^{-i\left(\frac{\omega_1 k}{a} + \frac{\omega_2 l}{a}\right)}, \tilde{\mathbf{Q}}^{h,i,-,-}\left(\frac{\omega_1}{a}, \frac{\omega_2}{a}\right) = \frac{1}{a^2} \sum_{k,l} \tilde{\mathbf{Q}}_{k,l}^{h,i,-,-} e^{-i\left(\frac{\omega_1 k}{a} + \frac{\omega_2 l}{a}\right)},\end{aligned}$$

($h=1, 2, \dots, a-1; i=1, 2, 3$) 为 $\tilde{\Psi}^{h,i}(x, y)$ 的双正, 正负, 双负面具符号。

定理 8: 若 $\Phi(x, y)$ 和 $\tilde{\Phi}(x, y)$ 是双正交二维四向多加细函数, $\Psi^{h,i}(x, y)$ 和 $\tilde{\Psi}^{h,i}(x, y)$ 是相应的双正交二维四向多小波函数, 则它们的面具符号满足

$$\begin{aligned}&\left\{ \sum_{k,l=0}^{a-1} \left\{ \mathbf{Q}^{m,s,+,+}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,+,+}(-p_1, -p_2) + \mathbf{Q}^{m,s,-,+}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,-,+}(-p_1, -p_2) \right. \right. \\ &\quad \left. \left. + \mathbf{Q}^{m,s,+,-}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,+,-}(-p_1, -p_2) + \mathbf{Q}^{m,s,-,-}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,-,-}(-p_1, -p_2) \right\} = \delta_{m,s} \delta_{n,t} \mathbf{I}_r \right. \\ &\quad \left. \sum_{k,l=0}^{a-1} \left\{ \mathbf{Q}^{m,s,+,+}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,+,-}(-p_1, p_2) + \mathbf{Q}^{m,s,+,-}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,+,+}(-p_1, p_2) \right. \right. \\ &\quad \left. \left. + \mathbf{Q}^{m,s,-,+}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,-,-}(-p_1, p_2) + \mathbf{Q}^{m,s,-,-}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,-,+}(-p_1, p_2) \right\} = \mathbf{O}_r \right. \\ &\quad \left. \sum_{k,l=0}^{a-1} \left\{ \mathbf{Q}^{m,s,+,+}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,-,+}(p_1, -p_2) + \mathbf{Q}^{m,s,+,-}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,-,-}(p_1, -p_2) \right. \right. \\ &\quad \left. \left. + \mathbf{Q}^{m,s,-,+}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,+,-}(p_1, -p_2) + \mathbf{Q}^{m,s,-,-}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,+,+}(p_1, -p_2) \right\} = \mathbf{O}_r \right. \\ &\quad \left. \sum_{k,l=0}^{a-1} \left\{ \mathbf{Q}^{m,s,+,+}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,-,-}(p_1, p_2) + \mathbf{Q}^{m,s,+,-}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,-,+}(p_1, p_2) \right. \right. \\ &\quad \left. \left. + \mathbf{Q}^{m,s,-,+}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,+,-}(p_1, p_2) + \mathbf{Q}^{m,s,-,-}(p_1, p_2) \tilde{\mathbf{Q}}^{n,t,+,+}(p_1, p_2) \right\} = \mathbf{O}_r \right.\end{aligned}\quad (19)$$

$$\begin{aligned}
& \left. \sum_{k,l=0}^{a-1} \left\{ \mathbf{P}^{+,+}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,+,+}(-p_1, -p_2) + \mathbf{P}^{-,+}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,-,+}(-p_1, -p_2) \right. \right. \\
& \quad \left. \left. + \mathbf{P}^{+,-}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,+,-}(-p_1, -p_2) + \mathbf{P}^{-,-}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,-,-}(-p_1, -p_2) \right\} = \mathbf{O}_r \right. \\
& \left. \sum_{k,l=0}^{a-1} \left\{ \mathbf{P}^{+,+}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,+,-}(-p_1, p_2) + \mathbf{P}^{+,-}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,+,+}(-p_1, p_2) \right. \right. \\
& \quad \left. \left. + \mathbf{P}^{-,+}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,-,-}(-p_1, p_2) + \mathbf{P}^{-,-}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,-,+}(-p_1, p_2) \right\} = \mathbf{O}_r \right. \\
& \left. \sum_{k,l=0}^{a-1} \left\{ \mathbf{P}^{+,+}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,-,+}(p_1, -p_2) + \mathbf{P}^{+,-}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,-,-}(p_1, -p_2) \right. \right. \\
& \quad \left. \left. + \mathbf{P}^{-,+}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,+,+}(p_1, -p_2) + \mathbf{P}^{-,-}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,+,-}(p_1, -p_2) \right\} = \mathbf{O}_r \right. \\
& \left. \sum_{k,l=0}^{a-1} \left\{ \mathbf{P}^{+,+}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,-,-}(p_1, p_2) + \mathbf{P}^{+,-}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,-,+}(p_1, p_2) \right. \right. \\
& \quad \left. \left. + \mathbf{P}^{-,+}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,+,-}(p_1, p_2) + \mathbf{P}^{-,-}(p_1, p_2) \tilde{\mathbf{Q}}^{h,i,+,+}(p_1, p_2) \right\} = \mathbf{O}_r \right. \\
& \left. \sum_{k,l=0}^{a-1} \left\{ \tilde{\mathbf{P}}^{+,+}(p_1, p_2) \mathbf{Q}^{h,i,+,+}(-p_1, -p_2) + \tilde{\mathbf{P}}^{+,-}(p_1, p_2) \mathbf{Q}^{h,i,-,+}(-p_1, -p_2) \right. \right. \\
& \quad \left. \left. + \tilde{\mathbf{P}}^{-,+}(p_1, p_2) \mathbf{Q}^{h,i,+,-}(-p_1, -p_2) + \tilde{\mathbf{P}}^{-,-}(p_1, p_2) \mathbf{Q}^{h,i,-,-}(-p_1, -p_2) \right\} = \mathbf{O}_r \right. \\
& \left. \sum_{k,l=0}^{a-1} \left\{ \tilde{\mathbf{P}}^{+,+}(p_1, p_2) \mathbf{Q}^{h,i,+,-}(-p_1, p_2) + \tilde{\mathbf{P}}^{+,-}(p_1, p_2) \mathbf{Q}^{h,i,+,+}(-p_1, p_2) \right. \right. \\
& \quad \left. \left. + \tilde{\mathbf{P}}^{-,+}(p_1, p_2) \mathbf{Q}^{h,i,-,-}(-p_1, p_2) + \tilde{\mathbf{P}}^{-,-}(p_1, p_2) \mathbf{Q}^{h,i,-,+}(-p_1, p_2) \right\} = \mathbf{O}_r \right. \\
& \left. \sum_{k,l=0}^{a-1} \left\{ \tilde{\mathbf{P}}^{+,+}(p_1, p_2) \mathbf{Q}^{h,i,-,+}(p_1, -p_2) + \tilde{\mathbf{P}}^{+,-}(p_1, p_2) \mathbf{Q}^{h,i,-,-}(p_1, -p_2) \right. \right. \\
& \quad \left. \left. + \tilde{\mathbf{P}}^{-,+}(p_1, p_2) \mathbf{Q}^{h,i,+,+}(p_1, -p_2) + \tilde{\mathbf{P}}^{-,-}(p_1, p_2) \mathbf{Q}^{h,i,+,-}(p_1, -p_2) \right\} = \mathbf{O}_r \right. \\
& \left. \sum_{k,l=0}^{a-1} \left\{ \tilde{\mathbf{P}}^{+,+}(p_1, p_2) \mathbf{Q}^{h,i,-,-}(p_1, p_2) + \tilde{\mathbf{P}}^{+,-}(p_1, p_2) \mathbf{Q}^{h,i,-,+}(p_1, p_2) \right. \right. \\
& \quad \left. \left. + \tilde{\mathbf{P}}^{-,+}(p_1, p_2) \mathbf{Q}^{h,i,+,-}(p_1, p_2) + \tilde{\mathbf{P}}^{-,-}(p_1, p_2) \mathbf{Q}^{h,i,+,+}(p_1, p_2) \right\} = \mathbf{O}_r \right.
\end{aligned} \tag{20}$$

其中: $h, m, n = 1, 2, \dots, a-1$; $i, s, t = 1, 2, 3$; $p_1 = \omega_1 + \frac{2k\pi}{a}$; $p_2 = \omega_2 + \frac{2l\pi}{a}$ 。

证明: 根据(16)式的正交性易得。

5. 构造算法

定理 9: 如果 $\Phi(x, y)$ 和 $\tilde{\Phi}(x, y)$ 是双正交二维四向多加细函数, $\Psi^{h,i}(x, y)$ 和 $\tilde{\Psi}^{h,i}(x, y)$ 是相应的双正交二维四向多小波函数, $\mathbf{P}(\omega_1, \omega_2)$, $\tilde{\mathbf{P}}(\omega_1, \omega_2)$ 和 $\mathbf{Q}^{h,i}(\omega_1, \omega_2)$, $\tilde{\mathbf{Q}}^{h,i}(\omega_1, \omega_2)$ 是矩阵符号, 构造

$$\begin{cases}
\mathbf{P}^{+,+}(\omega_1, \omega_2) = \lambda_0(\omega_1, \omega_2) \mathbf{P}(\omega_1, \omega_2) + \sum_{j=1}^{a-1} \lambda_j(\omega_1, \omega_2) \mathbf{Q}^{h,i}(\omega_1, \omega_2), \\
\mathbf{P}^{+,-}(\omega_1, \omega_2) = \lambda_a(\omega_1, \omega_2) \mathbf{P}(\omega_1, -\omega_2) + \sum_{j=a+1}^{2a-1} \lambda_j(\omega_1, \omega_2) \mathbf{Q}^{h,i}(\omega_1, -\omega_2), \\
\mathbf{P}^{-,+}(\omega_1, \omega_2) = \lambda_{2a}(\omega_1, \omega_2) \mathbf{P}(-\omega_1, \omega_2) + \sum_{j=2a+1}^{3a-1} \lambda_j(\omega_1, \omega_2) \mathbf{Q}^{h,i}(-\omega_1, \omega_2), \\
\mathbf{P}^{-,-}(\omega_1, \omega_2) = \lambda_{3a}(\omega_1, \omega_2) \mathbf{P}(-\omega_1, -\omega_2) + \sum_{j=3a+1}^{4a-1} \lambda_j(\omega_1, \omega_2) \mathbf{Q}^{h,i}(-\omega_1, -\omega_2);
\end{cases}$$

$$\begin{cases} \tilde{\mathbf{P}}^{+,+}(\omega_1, \omega_2) = \tilde{\lambda}_0(\omega_1, \omega_2) \tilde{\mathbf{P}}(\omega_1, \omega_2) + \sum_{j=1}^{a-1} \tilde{\lambda}_j(\omega_1, \omega_2) \tilde{\mathbf{Q}}^{h,i}(\omega_1, \omega_2), \\ \tilde{\mathbf{P}}^{+,-}(\omega_1, \omega_2) = \tilde{\lambda}_a(\omega_1, \omega_2) \tilde{\mathbf{P}}(\omega_1, -\omega_2) + \sum_{j=a+1}^{2a-1} \tilde{\lambda}_j(\omega_1, \omega_2) \tilde{\mathbf{Q}}^{h,i}(\omega_1, -\omega_2), \\ \tilde{\mathbf{P}}^{-,+}(\omega_1, \omega_2) = \tilde{\lambda}_{2a}(\omega_1, \omega_2) \tilde{\mathbf{P}}(-\omega_1, \omega_2) + \sum_{j=2a+1}^{3a-1} \tilde{\lambda}_j(\omega_1, \omega_2) \tilde{\mathbf{Q}}^{h,i}(-\omega_1, \omega_2), \\ \tilde{\mathbf{P}}^{-,-}(\omega_1, \omega_2) = \tilde{\lambda}_{3a}(\omega_1, \omega_2) \tilde{\mathbf{P}}(-\omega_1, -\omega_2) + \sum_{j=3a+1}^{4a-1} \tilde{\lambda}_j(\omega_1, \omega_2) \tilde{\mathbf{Q}}^{h,i}(-\omega_1, -\omega_2). \end{cases}$$

($h : 0 \leq h \leq a-10 \leq h \leq 4a-1; i : 1 \leq i \leq 3; i, h \in \mathbb{Z}^+$)。函数 $\lambda_j(\omega_1, \omega_2)$ 和 $\tilde{\lambda}_j(\omega_1, \omega_2)$ 以 $\frac{2\pi}{a}$ 为周期, 且满足

$$1) \quad \begin{cases} \sum_{j=0}^{4a-1} \lambda_j(\omega_1, \omega_2) \tilde{\lambda}_j(-\omega_1, -\omega_2) = 1, \\ \sum_{j=0}^{a-1} \{\lambda_j(\omega_1, \omega_2) \tilde{\lambda}_{a+j}(-\omega_1, -\omega_2) + \lambda_{2a+j}(\omega_1, \omega_2) \tilde{\lambda}_{3a+j}(-\omega_1, -\omega_2)\} = 0, \\ \sum_{j=0}^{a-1} \{\lambda_j(\omega_1, \omega_2) \tilde{\lambda}_{2a+j}(-\omega_1, -\omega_2) + \lambda_{a+j}(\omega_1, \omega_2) \tilde{\lambda}_{3a+j}(-\omega_1, -\omega_2)\} = 0, \\ \sum_{j=0}^{a-1} \{\lambda_j(\omega_1, \omega_2) \tilde{\lambda}_{3a+j}(-\omega_1, -\omega_2) + \lambda_{a+j}(\omega_1, \omega_2) \tilde{\lambda}_{2a+j}(-\omega_1, -\omega_2)\} = 0, \\ \lambda_0(0,0) + \lambda_a(0,0) + \lambda_{2a}(0,0) + \lambda_{3a}(0,0) = 1, \\ \tilde{\lambda}_0(0,0) + \tilde{\lambda}_a(0,0) + \tilde{\lambda}_{2a}(0,0) + \tilde{\lambda}_{3a}(0,0) = 1, \\ |\lambda_0(0,0) - \lambda_a(0,0) - \lambda_{2a}(0,0) + \lambda_{3a}(0,0)| < 1, \\ |\tilde{\lambda}_0(0,0) - \tilde{\lambda}_a(0,0) - \tilde{\lambda}_{2a}(0,0) + \tilde{\lambda}_{3a}(0,0)| < 1, \\ |\lambda_0(0,0) + \lambda_a(0,0) - \lambda_{2a}(0,0) - \lambda_{3a}(0,0)| < 1, \\ |\tilde{\lambda}_0(0,0) + \tilde{\lambda}_a(0,0) - \tilde{\lambda}_{2a}(0,0) - \tilde{\lambda}_{3a}(0,0)| < 1, \\ |\lambda_0(0,0) - \lambda_a(0,0) + \lambda_{2a}(0,0) - \lambda_{3a}(0,0)| < 1, \\ |\tilde{\lambda}_0(0,0) - \tilde{\lambda}_a(0,0) + \tilde{\lambda}_{2a}(0,0) - \tilde{\lambda}_{3a}(0,0)| < 1; \end{cases}$$

$$2) \quad \begin{cases} \sum_{j=0}^{4a-1} \lambda_j(\omega_1, \omega_2) \tilde{\lambda}_j(-\omega_1, -\omega_2) = 1, \\ \sum_{j=0}^{a-1} \{\lambda_j(\omega_1, \omega_2) \tilde{\lambda}_{a+j}(-\omega_1, -\omega_2) + \lambda_{2a+j}(\omega_1, \omega_2) \tilde{\lambda}_{3a+j}(-\omega_1, -\omega_2)\} = 0, \\ \sum_{j=0}^{a-1} \{\lambda_j(\omega_1, \omega_2) \tilde{\lambda}_{2a+j}(-\omega_1, -\omega_2) + \lambda_{a+j}(\omega_1, \omega_2) \tilde{\lambda}_{3a+j}(-\omega_1, -\omega_2)\} = 0, \\ \sum_{j=0}^{a-1} \{\lambda_j(\omega_1, \omega_2) \tilde{\lambda}_{3a+j}(-\omega_1, -\omega_2) + \lambda_{a+j}(\omega_1, \omega_2) \tilde{\lambda}_{2a+j}(-\omega_1, -\omega_2)\} = 0, \\ |\lambda_0(0,0) + \lambda_a(0,0) + \lambda_{2a}(0,0) + \lambda_{3a}(0,0)| < 1, \\ |\tilde{\lambda}_0(0,0) + \tilde{\lambda}_a(0,0) + \tilde{\lambda}_{2a}(0,0) + \tilde{\lambda}_{3a}(0,0)| < 1, \\ \lambda_0(0,0) - \lambda_a(0,0) - \lambda_{2a}(0,0) + \lambda_{3a}(0,0) = 1, \\ \tilde{\lambda}_0(0,0) - \tilde{\lambda}_a(0,0) - \tilde{\lambda}_{2a}(0,0) + \tilde{\lambda}_{3a}(0,0) = 1, \\ |\lambda_0(0,0) + \lambda_a(0,0) - \lambda_{2a}(0,0) - \lambda_{3a}(0,0)| < 1, \\ |\tilde{\lambda}_0(0,0) + \tilde{\lambda}_a(0,0) - \tilde{\lambda}_{2a}(0,0) - \tilde{\lambda}_{3a}(0,0)| < 1, \\ |\lambda_0(0,0) - \lambda_a(0,0) + \lambda_{2a}(0,0) - \lambda_{3a}(0,0)| < 1, \\ |\tilde{\lambda}_0(0,0) - \tilde{\lambda}_a(0,0) + \tilde{\lambda}_{2a}(0,0) - \tilde{\lambda}_{3a}(0,0)| < 1; \end{cases}$$

$$\begin{aligned}
& \sum_{j=0}^{4a-1} \lambda_j(\omega_1, \omega_2) \tilde{\lambda}_j(-\omega_1, -\omega_2) = 1, \\
& \sum_{j=0}^{a-1} \left\{ \lambda_j(\omega_1, \omega_2) \tilde{\lambda}_{a+j}(-\omega_1, -\omega_2) + \lambda_{2a+j}(\omega_1, \omega_2) \tilde{\lambda}_{3a+j}(-\omega_1, -\omega_2) \right\} = 0, \\
& \sum_{j=0}^{a-1} \left\{ \lambda_j(\omega_1, \omega_2) \tilde{\lambda}_{2a+j}(-\omega_1, -\omega_2) + \lambda_{a+j}(\omega_1, \omega_2) \tilde{\lambda}_{3a+j}(-\omega_1, -\omega_2) \right\} = 0, \\
& \sum_{j=0}^{a-1} \left\{ \lambda_j(\omega_1, \omega_2) \tilde{\lambda}_{3a+j}(-\omega_1, -\omega_2) + \lambda_{a+j}(\omega_1, \omega_2) \tilde{\lambda}_{2a+j}(-\omega_1, -\omega_2) \right\} = 0, \\
3) & \quad \left| \lambda_0(0,0) + \lambda_a(0,0) + \lambda_{2a}(0,0) + \lambda_{3a}(0,0) \right| < 1, \\
& \quad \left| \tilde{\lambda}_0(0,0) + \tilde{\lambda}_a(0,0) + \tilde{\lambda}_{2a}(0,0) + \tilde{\lambda}_{3a}(0,0) \right| < 1, \\
& \quad \left| \lambda_0(0,0) - \lambda_a(0,0) - \lambda_{2a}(0,0) + \lambda_{3a}(0,0) \right| < 1, \\
& \quad \left| \tilde{\lambda}_0(0,0) - \tilde{\lambda}_a(0,0) - \tilde{\lambda}_{2a}(0,0) + \tilde{\lambda}_{3a}(0,0) \right| < 1, \\
& \quad \lambda_0(0,0) + \lambda_a(0,0) - \lambda_{2a}(0,0) - \lambda_{3a}(0,0) = 1, \\
& \quad \tilde{\lambda}_0(0,0) + \tilde{\lambda}_a(0,0) - \tilde{\lambda}_{2a}(0,0) - \tilde{\lambda}_{3a}(0,0) = 1, \\
& \quad \left| \lambda_0(0,0) - \lambda_a(0,0) + \lambda_{2a}(0,0) - \lambda_{3a}(0,0) \right| < 1, \\
& \quad \left| \tilde{\lambda}_0(0,0) - \tilde{\lambda}_a(0,0) + \tilde{\lambda}_{2a}(0,0) - \tilde{\lambda}_{3a}(0,0) \right| < 1; \\
& \sum_{j=0}^{4a-1} \lambda_j(\omega_1, \omega_2) \tilde{\lambda}_j(-\omega_1, -\omega_2) = 1, \\
& \sum_{j=0}^{a-1} \left\{ \lambda_j(\omega_1, \omega_2) \tilde{\lambda}_{a+j}(-\omega_1, -\omega_2) + \lambda_{2a+j}(\omega_1, \omega_2) \tilde{\lambda}_{3a+j}(-\omega_1, -\omega_2) \right\} = 0, \\
& \sum_{j=0}^{a-1} \left\{ \lambda_j(\omega_1, \omega_2) \tilde{\lambda}_{2a+j}(-\omega_1, -\omega_2) + \lambda_{a+j}(\omega_1, \omega_2) \tilde{\lambda}_{3a+j}(-\omega_1, -\omega_2) \right\} = 0, \\
& \sum_{j=0}^{a-1} \left\{ \lambda_j(\omega_1, \omega_2) \tilde{\lambda}_{3a+j}(-\omega_1, -\omega_2) + \lambda_{a+j}(\omega_1, \omega_2) \tilde{\lambda}_{2a+j}(-\omega_1, -\omega_2) \right\} = 0, \\
4) & \quad \left| \lambda_0(0,0) + \lambda_a(0,0) + \lambda_{2a}(0,0) + \lambda_{3a}(0,0) \right| < 1, \\
& \quad \left| \tilde{\lambda}_0(0,0) + \tilde{\lambda}_a(0,0) + \tilde{\lambda}_{2a}(0,0) + \tilde{\lambda}_{3a}(0,0) \right| < 1, \\
& \quad \left| \lambda_0(0,0) - \lambda_a(0,0) - \lambda_{2a}(0,0) + \lambda_{3a}(0,0) \right| < 1, \\
& \quad \left| \tilde{\lambda}_0(0,0) - \tilde{\lambda}_a(0,0) - \tilde{\lambda}_{2a}(0,0) + \tilde{\lambda}_{3a}(0,0) \right| < 1, \\
& \quad \left| \lambda_0(0,0) + \lambda_a(0,0) - \lambda_{2a}(0,0) - \lambda_{3a}(0,0) \right| < 1, \\
& \quad \left| \tilde{\lambda}_0(0,0) + \tilde{\lambda}_a(0,0) - \tilde{\lambda}_{2a}(0,0) - \tilde{\lambda}_{3a}(0,0) \right| < 1, \\
& \quad \lambda_0(0,0) - \lambda_a(0,0) + \lambda_{2a}(0,0) - \lambda_{3a}(0,0) = 1, \\
& \quad \tilde{\lambda}_0(0,0) - \tilde{\lambda}_a(0,0) + \tilde{\lambda}_{2a}(0,0) - \tilde{\lambda}_{3a}(0,0) = 1;
\end{aligned}$$

则 $\mathbf{P}^{+,+}(\omega_1, \omega_2), \mathbf{P}^{+,-}(\omega_1, \omega_2), \mathbf{P}^{-,+}(\omega_1, \omega_2), \mathbf{P}^{-,-}(\omega_1, \omega_2)$ 和 $\tilde{\mathbf{P}}^{+,+}(\omega_1, \omega_2), \tilde{\mathbf{P}}^{+,-}(\omega_1, \omega_2), \tilde{\mathbf{P}}^{-,+}(\omega_1, \omega_2), \tilde{\mathbf{P}}^{-,-}(\omega_1, \omega_2)$, 产生一个双正交二维四向多细分函数 $\Phi(x, y)$ 并满足 $\Phi(x, y) = \sum_{k,l} \mathbf{P}_{l,k}^{+,+} \Phi(ax - k, ay - l) + \sum_{k,l} \mathbf{P}_{l,k}^{+,-} \Phi(ax - k, l - ay) + \sum_{k,l} \mathbf{P}_{l,k}^{-,+} \Phi(k - ax, ay - l) + \sum_{k,l} \mathbf{P}_{l,k}^{-,-} \Phi(k - ax, l - ay)$.

$$\tilde{\Phi}(x, y) = \sum_{k,l} \tilde{\mathbf{P}}_{l,k}^{+,+} \tilde{\Phi}(ax - k, ay - l) + \sum_{k,l} \tilde{\mathbf{P}}_{l,k}^{+,-} \tilde{\Phi}(ax - k, l - ay) + \sum_{k,l} \tilde{\mathbf{P}}_{l,k}^{-,+} \tilde{\Phi}(k - ax, ay - l) + \sum_{k,l} \tilde{\mathbf{P}}_{l,k}^{-,-} \tilde{\Phi}(k - ax, l - ay).$$

证明: 将上面已经构造的 $\mathbf{P}^{+,+}(\omega_1, \omega_2), \mathbf{P}^{+,-}(\omega_1, \omega_2), \mathbf{P}^{-,+}(\omega_1, \omega_2), \mathbf{P}^{-,-}(\omega_1, \omega_2)$ 和 $\tilde{\mathbf{P}}^{+,+}(\omega_1, \omega_2), \tilde{\mathbf{P}}^{+,-}(\omega_1, \omega_2), \tilde{\mathbf{P}}^{-,+}(\omega_1, \omega_2), \tilde{\mathbf{P}}^{-,-}(\omega_1, \omega_2)$, 代入(15)式化简可得。再令(11)式 $\mathbf{P}(\omega_1, \omega_2) = \mathbf{P}(0, 0)$, 则化简 $\mathbf{P}(0, 0)$ 并求特征值可证得定理。

定理 10：如果 $\Phi(x, y)$ 和 $\tilde{\Phi}(x, y)$ 是双正交二维四向多加细函数， $\Psi^{h,i}(x, y)$ 和 $\tilde{\Psi}^{h,i}(x, y)$ 是相应的双正交二维四向多小波函数， $P(\omega_1, \omega_2), \tilde{P}(\omega_1, \omega_2)$ 和 $Q^{j,s}(\omega_1, \omega_2), \tilde{Q}^{j,s}(\omega_1, \omega_2)$ 是面具符号，构造

$$\left\{ \begin{array}{l} Q^{h,i,+,+}(\omega_1, \omega_2) = \mu_0^{h,i}(\omega_1, \omega_2) P(\omega_1, \omega_2) + \sum_{j=1}^{a-1} \mu_j^{h,i}(\omega_1, \omega_2) Q^{j,s}(\omega_1, \omega_2), \\ Q^{h,i,+,-}(\omega_1, \omega_2) = \mu_a^{h,i}(\omega_1, \omega_2) P(\omega_1, -\omega_2) + \sum_{j=a+1}^{2a-1} \mu_j^{h,i}(\omega_1, \omega_2) Q^{j,s}(\omega_1, -\omega_2), \\ Q^{h,i,-,+}(\omega_1, \omega_2) = \mu_{2a}^{h,i}(\omega_1, \omega_2) P(-\omega_1, \omega_2) + \sum_{j=2a+1}^{3a-1} \mu_j^{h,i}(\omega_1, \omega_2) Q^{j,s}(-\omega_1, \omega_2), \\ Q^{h,i,-,-}(\omega_1, \omega_2) = \mu_{3a}^{h,i}(\omega_1, \omega_2) P(-\omega_1, -\omega_2) + \sum_{j=3a+1}^{4a-1} \mu_j^{h,i}(\omega_1, \omega_2) Q^{j,s}(-\omega_1, -\omega_2); \\ \\ \tilde{Q}^{h,i,+,+}(\omega_1, \omega_2) = \tilde{\mu}_0^{h,i}(\omega_1, \omega_2) \tilde{P}(\omega_1, \omega_2) + \sum_{j=1}^{a-1} \tilde{\mu}_j^{h,i}(\omega_1, \omega_2) \tilde{Q}^{j,s}(\omega_1, \omega_2), \\ \tilde{Q}^{h,i,+,-}(\omega_1, \omega_2) = \tilde{\mu}_a^{h,i}(\omega_1, \omega_2) \tilde{P}(\omega_1, -\omega_2) + \sum_{j=a+1}^{2a-1} \tilde{\mu}_j^{h,i}(\omega_1, \omega_2) \tilde{Q}^{j,s}(\omega_1, -\omega_2), \\ \tilde{Q}^{h,i,-,+}(\omega_1, \omega_2) = \tilde{\mu}_{2a}^{h,i}(\omega_1, \omega_2) \tilde{P}(-\omega_1, \omega_2) + \sum_{j=2a+1}^{3a-1} \tilde{\mu}_j^{h,i}(\omega_1, \omega_2) \tilde{Q}^{j,s}(-\omega_1, \omega_2), \\ \tilde{Q}^{h,i,-,-}(\omega_1, \omega_2) = \tilde{\mu}_{3a}^{h,i}(\omega_1, \omega_2) \tilde{P}(-\omega_1, -\omega_2) + \sum_{j=3a+1}^{4a-1} \tilde{\mu}_j^{h,i}(\omega_1, \omega_2) \tilde{Q}^{j,s}(-\omega_1, -\omega_2). \end{array} \right.$$

$(h : 0 \leq h \leq a-10 \leq h \leq 4a-1; i, s : 1 \leq i, s \leq 3; i, h, s \in Z^+)$ 。函数 $\lambda_j(\omega_1, \omega_2), \mu_j^{h,i}(\omega_1, \omega_2)$ 和 $\tilde{\mu}_j^{h,i}(\omega_1, \omega_2)$ 以 $\frac{2\pi}{a}$ 为周期，且满足

$$1) \quad \left\{ \begin{array}{l} \sum_{j=0}^{4a-1} \lambda_j(\omega_1, \omega_2) \tilde{\mu}_j^{h,i}(-\omega_1, -\omega_2) = 0, \\ \sum_{j=0}^{4a-1} \tilde{\lambda}_j(\omega_1, \omega_2) \mu_j^{h,i}(-\omega_1, -\omega_2) = 0, \\ \sum_{j=0}^{a-1} \lambda_j(\omega_1, \omega_2) \tilde{\mu}_{j+a}^{h,i}(-\omega_1, -\omega_2) + \lambda_{j+a}(\omega_1, \omega_2) \tilde{\mu}_j^{h,i}(-\omega_1, -\omega_2) \\ \quad + \lambda_{j+2a}(\omega_1, \omega_2) \tilde{\mu}_{j+3a}^{h,i}(-\omega_1, -\omega_2) + \lambda_{j+3a}(\omega_1, \omega_2) \tilde{\mu}_{j+2a}^{h,i}(-\omega_1, -\omega_2) = 0, \\ \sum_{j=0}^{a-1} \tilde{\lambda}_j(\omega_1, \omega_2) \mu_{j+a}^{h,i}(-\omega_1, -\omega_2) + \tilde{\lambda}_{j+a}(\omega_1, \omega_2) \mu_j^{h,i}(-\omega_1, -\omega_2) \\ \quad + \tilde{\lambda}_{j+2a}(\omega_1, \omega_2) \mu_{j+3a}^{h,i}(-\omega_1, -\omega_2) + \tilde{\lambda}_{j+3a}(\omega_1, \omega_2) \mu_{j+2a}^{h,i}(-\omega_1, -\omega_2) = 0, \\ \sum_{j=0}^{a-1} \lambda_j(\omega_1, \omega_2) \tilde{\mu}_{j+2a}^{h,i}(-\omega_1, -\omega_2) + \lambda_{j+2a}(\omega_1, \omega_2) \tilde{\mu}_j^{h,i}(-\omega_1, -\omega_2) \\ \quad + \lambda_{j+a}(\omega_1, \omega_2) \tilde{\mu}_{j+3a}^{h,i}(-\omega_1, -\omega_2) + \lambda_{j+3a}(\omega_1, \omega_2) \tilde{\mu}_{j+2a}^{h,i}(-\omega_1, -\omega_2) = 0, \\ \sum_{j=0}^{a-1} \tilde{\lambda}_j(\omega_1, \omega_2) \mu_{j+2a}^{h,i}(-\omega_1, -\omega_2) + \tilde{\lambda}_{j+2a}(\omega_1, \omega_2) \mu_j^{h,i}(-\omega_1, -\omega_2) \\ \quad + \tilde{\lambda}_{j+a}(\omega_1, \omega_2) \mu_{j+3a}^{h,i}(-\omega_1, -\omega_2) + \tilde{\lambda}_{j+3a}(\omega_1, \omega_2) \mu_{j+2a}^{h,i}(-\omega_1, -\omega_2) = 0, \\ \sum_{j=0}^{a-1} \lambda_j(\omega_1, \omega_2) \tilde{\mu}_{j+3a}^{h,i}(-\omega_1, -\omega_2) + \lambda_{j+3a}(\omega_1, \omega_2) \tilde{\mu}_j^{h,i}(-\omega_1, -\omega_2) \\ \quad + \lambda_{j+a}(\omega_1, \omega_2) \tilde{\mu}_{j+2a}^{h,i}(-\omega_1, -\omega_2) + \lambda_{j+2a}(\omega_1, \omega_2) \tilde{\mu}_{j+a}^{h,i}(-\omega_1, -\omega_2) = 0, \\ \sum_{j=0}^{a-1} \tilde{\lambda}_j(\omega_1, \omega_2) \mu_{j+3a}^{h,i}(-\omega_1, -\omega_2) + \tilde{\lambda}_{j+3a}(\omega_1, \omega_2) \mu_j^{h,i}(-\omega_1, -\omega_2) \\ \quad + \tilde{\lambda}_{j+a}(\omega_1, \omega_2) \mu_{j+2a}^{h,i}(-\omega_1, -\omega_2) + \tilde{\lambda}_{j+2a}(\omega_1, \omega_2) \mu_{j+a}^{h,i}(-\omega_1, -\omega_2) = 0, \end{array} \right.$$

$$2) \quad \left\{ \begin{array}{l} \sum_{j=0}^{4a-1} \mu_j^{h,k}(\omega_1, \omega_2) \tilde{\mu}_j^{s,t}(-\omega_1, -\omega_2) = \delta_{h,s} \delta_{k,t}, \\ \sum_{j=0}^{a-1} \left\{ \mu_j^{h,i}(\omega_1, \omega_2) \tilde{\mu}_{a+j}^{h,i}(-\omega_1, -\omega_2) + \mu_{2a+j}^{h,i}(\omega_1, \omega_2) \tilde{\mu}_{3a+j}^{h,i}(-\omega_1, -\omega_2) \right\} = 0, \\ \sum_{j=0}^{a-1} \left\{ \mu_j^{h,i}(\omega_1, \omega_2) \tilde{\mu}_{2a+j}^{h,i}(-\omega_1, -\omega_2) + \mu_{a+j}^{h,i}(\omega_1, \omega_2) \tilde{\mu}_{3a+j}^{h,i}(-\omega_1, -\omega_2) \right\} = 0, \\ \sum_{j=0}^{a-1} \left\{ \mu_j^{h,i}(\omega_1, \omega_2) \tilde{\mu}_{3a+j}^{h,i}(-\omega_1, -\omega_2) + \mu_{a+j}^{h,i}(\omega_1, \omega_2) \tilde{\mu}_{2a+j}^{h,i}(-\omega_1, -\omega_2) \right\} = 0; \end{array} \right.$$

那么就可以得出 $\mathbf{Q}^{h,i,+,+}(\omega_1, \omega_2), \mathbf{Q}^{h,i,+,-}(\omega_1, \omega_2), \mathbf{Q}^{h,i,-,+}(\omega_1, \omega_2), \mathbf{Q}^{h,i,-,-}(\omega_1, \omega_2)$ 和 $\tilde{\mathbf{Q}}^{h,i,+,+}(\omega_1, \omega_2), \tilde{\mathbf{Q}}^{h,i,+,-}(\omega_1, \omega_2), \tilde{\mathbf{Q}}^{h,i,-,+}(\omega_1, \omega_2), \tilde{\mathbf{Q}}^{h,i,-,-}(\omega_1, \omega_2)$ 产生一个双正交二维四向多小波函数 $\Phi(x, y)$ 并满足

$$\begin{aligned} \Psi^{h,i}(x, y) &= \sum_{k,l} \mathbf{Q}_{k,l}^{h,i,+,+} \Phi(ax-k, ay-l) + \sum_{k,l} \mathbf{Q}_{k,l}^{h,i,+,-} \Phi(ax-k, l-ay) \\ &\quad + \sum_{k,l} \mathbf{Q}_{k,l}^{h,i,-,+} \Phi(k-ax, ay-l) + \sum_{k,l} \mathbf{Q}_{k,l}^{h,i,-,-} \Phi(k-ax, l-ay); \\ \tilde{\Psi}^{h,i}(x, y) &= \sum_{k,l} \tilde{\mathbf{Q}}_{k,l}^{h,i,+,+} \tilde{\Phi}(ax-k, ay-l) + \sum_{k,l} \tilde{\mathbf{Q}}_{k,l}^{h,i,+,-} \tilde{\Phi}(ax-k, l-ay) \\ &\quad + \sum_{k,l} \tilde{\mathbf{Q}}_{k,l}^{h,i,-,+} \tilde{\Phi}(k-ax, ay-l) + \sum_{k,l} \tilde{\mathbf{Q}}_{k,l}^{h,i,-,-} \tilde{\Phi}(k-ax, l-ay). \end{aligned}$$

证明：由于 $\Phi(x, y)$, $\tilde{\Phi}(x, y)$ 和 $\Psi^{h,i}(x, y)$, $\tilde{\Psi}^{h,i}(x, y)$ 的双正交性，可以将已构造的 $\mathbf{Q}^{h,i,+,+}(\omega_1, \omega_2), \mathbf{Q}^{h,i,+,-}(\omega_1, \omega_2), \mathbf{Q}^{h,i,-,+}(\omega_1, \omega_2), \mathbf{Q}^{h,i,-,-}(\omega_1, \omega_2)$ 和 $\tilde{\mathbf{Q}}^{h,i,+,+}(\omega_1, \omega_2), \tilde{\mathbf{Q}}^{h,i,+,-}(\omega_1, \omega_2), \tilde{\mathbf{Q}}^{h,i,-,+}(\omega_1, \omega_2), \tilde{\mathbf{Q}}^{h,i,-,-}(\omega_1, \omega_2)$ ，代入(16)式和(19)式化简可证得定理。

6. Mallat 算法

如果 $\Phi(x, y)$ 和 $\tilde{\Phi}(x, y)$ 是双正交二维四向多加细函数， $\Psi^{h,i}(x, y)$ 和 $\tilde{\Psi}^{h,i}(x, y)$ 是相应的双正交二维四向多小波函数，对于能量有限信号 $f(x, y) \in L(\mathbf{R}^2)$ 在分辨率 a_j 下的近似函数 $f_j(x, y) \in V_j$ ，则 V_{j+1} 可分解为 $V_{j+1} = V_j \oplus W_j = V_j \bigoplus_{h=1}^{a-1} \{W_j^{h,1} \oplus W_j^{h,2} \oplus W_j^{h,3}\}$ ，则 $\forall f_{j+1}(x, y) \in V_{j+1}$ ，记 $\mathbf{c}_{j,k_1,k_2} = [c_{j,k_1,k_2}^1, c_{j,k_1,k_2}^2, \dots, c_{j,k_1,k_2}^r]^T$ ，
 $\mathbf{d}_{j,k_1,k_2} = [d_{j,k_1,k_2}^1, d_{j,k_1,k_2}^2, \dots, d_{j,k_1,k_2}^r]^T$ 有

$$\begin{aligned} f_{j+1}(x, y) &= \sum_{k_1, k_2} \mathbf{c}_{j+1, k_1, k_2}^{+,+} \Phi_{j+1, k_1, k_2}^{+,+} + \sum_{k_1, k_2} \mathbf{c}_{j+1, k_1, k_2}^{+,-} \Phi_{j+1, k_1, k_2}^{+,-} \\ &\quad + \sum_{k_1, k_2} \mathbf{c}_{j+1, k_1, k_2}^{-,+} \Phi_{j+1, k_1, k_2}^{-,+} + \sum_{k_1, k_2} \mathbf{c}_{j+1, k_1, k_2}^{-,-} \Phi_{j+1, k_1, k_2}^{-,-} \\ &= \sum_{k_1, k_2} \mathbf{c}_{j, k_1, k_2}^{+,+} \Phi_{j, k_1, k_2}^{+,+} + \sum_{k_1, k_2} \mathbf{c}_{j, k_1, k_2}^{+,-} \Phi_{j, k_1, k_2}^{+,-} + \sum_{k_1, k_2} \mathbf{c}_{j, k_1, k_2}^{-,+} \Phi_{j, k_1, k_2}^{-,+} \\ &\quad + \sum_{k_1, k_2} \mathbf{c}_{j, k_1, k_2}^{-,-} \Phi_{j, k_1, k_2}^{-,-} + \sum_{h=1}^{a-1} \sum_{r=1}^3 \left[\sum_{k_1, k_2} \mathbf{d}_{j, k_1, k_2}^{h, i, +, +} \Psi_{j, k_1, k_2}^{h, i, +, +} + \sum_{k_1, k_2} \mathbf{d}_{j, k_1, k_2}^{h, i, +, -, -} \Psi_{j, k_1, k_2}^{h, i, +, -, -} \right. \\ &\quad \left. + \sum_{k_1, k_2} \mathbf{d}_{j, k_1, k_2}^{h, i, -, +} \Psi_{j, k_1, k_2}^{h, i, -, +} + \sum_{k_1, k_2} \mathbf{d}_{j, k_1, k_2}^{h, i, -, -, -} \Psi_{j, k_1, k_2}^{h, i, -, -, -} \right] \end{aligned}$$

6.1. 分解算法

如果 $f(x, y)$ 在分辨率 a_{j+1} 下的近似函数为 $f_{j+1}(x, y)$ ，那么它可以进一步分解为 $f(x, y)$ 在 a_j 下的

主要部分(通过低通滤波器得到)和细节部分(通过高通滤波器得到)。即分解算法要实现的目标就是: 已知

$$\mathbf{c}_{j+1,k_1,k_2}^{+,+}, \mathbf{c}_{j+1,k_1,k_2}^{+,-}, \mathbf{c}_{j+1,k_1,k_2}^{-,+}, \mathbf{c}_{j+1,k_1,k_2}^{-,-}, \text{ 求 } \mathbf{c}_{j,k_1,k_2}^{+,+}, \mathbf{c}_{j,k_1,k_2}^{+,-}, \mathbf{c}_{j,k_1,k_2}^{-,+}, \text{ 和 } \mathbf{d}_{j,k_1,k_2}^{+,+}, \mathbf{d}_{j,k_1,k_2}^{+,-}, \mathbf{d}_{j,k_1,k_2}^{-,+}, \mathbf{d}_{j,k_1,k_2}^{-,-}。$$

$$\text{定理 11: 若 } f_{j+1}(x, y) = \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,+} \Phi_{j+1,k_1,k_2}^{+,+} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,-} \Phi_{j+1,k_1,k_2}^{+,-} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,+} \Phi_{j+1,k_1,k_2}^{-,+} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \Phi_{j+1,k_1,k_2}^{-,-}$$

并且由(1)式和(17)式, 我们可以得到下列分解公式

$$\begin{aligned} \mathbf{c}_{j,n_1,n_2}^{+,+} &= \frac{1}{a^2} \left[\sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,+} \overline{\mathbf{P}_{k_1-an_1, k_2-an_2}^{+,+}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,-} \overline{\mathbf{P}_{k_1-an_1, k_2-an_2}^{+,-}} \right. \\ &\quad \left. + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,+} \overline{\mathbf{P}_{k_1-an_1, k_2-an_2}^{-,+}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \overline{\mathbf{P}_{k_1-an_1, k_2-an_2}^{-,-}} \right]; \\ \mathbf{c}_{j,n_1,n_2}^{+,-} &= \frac{1}{a^2} \left[\sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,+} \overline{\mathbf{P}_{k_1-an_1, an_2-k_2}^{+,-}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,-} \overline{\mathbf{P}_{k_1-an_1, an_2-k_2}^{+,-}} \right. \\ &\quad \left. + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,+} \overline{\mathbf{P}_{k_1-an_1, an_2-k_2}^{-,+}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \overline{\mathbf{P}_{k_1-an_1, an_2-k_2}^{-,-}} \right]; \\ \mathbf{c}_{j,n_1,n_2}^{-,+} &= \frac{1}{a^2} \left[\sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,+} \overline{\mathbf{P}_{an_1-k_1, k_2-an_2}^{-,+}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,-} \overline{\mathbf{P}_{an_1-k_1, k_2-an_2}^{-,+}} \right. \\ &\quad \left. + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,+} \overline{\mathbf{P}_{an_1-k_1, k_2-an_2}^{-,+}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \overline{\mathbf{P}_{an_1-k_1, k_2-an_2}^{-,-}} \right]; \\ \mathbf{c}_{j,n_1,n_2}^{-,-} &= \frac{1}{a^2} \left[\sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,+} \overline{\mathbf{P}_{an_1-k_1, an_2-k_2}^{-,-}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,-} \overline{\mathbf{P}_{an_1-k_1, an_2-k_2}^{-,-}} \right. \\ &\quad \left. + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,+} \overline{\mathbf{P}_{an_1-k_1, an_2-k_2}^{-,+}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \overline{\mathbf{P}_{an_1-k_1, an_2-k_2}^{-,-}} \right]; \\ \mathbf{d}_{j,n_1,n_2}^{h,i,+,+} &= \frac{1}{a^2} \left[\sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,+} \overline{\mathbf{Q}_{k_1-an_1, k_2-an_2}^{h,i,+,+}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,-} \overline{\mathbf{Q}_{k_1-an_1, k_2-an_2}^{h,i,+,-}} \right. \\ &\quad \left. + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,+} \overline{\mathbf{Q}_{k_1-an_1, k_2-an_2}^{h,i,-,+}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \overline{\mathbf{Q}_{k_1-an_1, k_2-an_2}^{h,i,-,-}} \right]; \\ \mathbf{d}_{j,n_1,n_2}^{h,i,+,-} &= \frac{1}{a^2} \left[\sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,+} \overline{\mathbf{Q}_{k_1-an_1, an_2-k_2}^{h,i,+,-}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,-} \overline{\mathbf{Q}_{k_1-an_1, an_2-k_2}^{h,i,+,+}} \right. \\ &\quad \left. + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,+} \overline{\mathbf{Q}_{k_1-an_1, an_2-k_2}^{h,i,-,-}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \overline{\mathbf{Q}_{k_1-an_1, an_2-k_2}^{h,i,-,+}} \right]; \\ \mathbf{d}_{j,n_1,n_2}^{h,i,-,+} &= \frac{1}{a^2} \left[\sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,+} \overline{\mathbf{Q}_{an_1-k_1, k_2-an_2}^{h,i,-,+}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,-} \overline{\mathbf{Q}_{an_1-k_1, k_2-an_2}^{h,i,-,-}} \right. \\ &\quad \left. + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,+} \overline{\mathbf{Q}_{an_1-k_1, k_2-an_2}^{h,i,+,-}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \overline{\mathbf{Q}_{an_1-k_1, k_2-an_2}^{h,i,+,+}} \right]; \\ \mathbf{d}_{j,n_1,n_2}^{h,i,-,-} &= \frac{1}{a^2} \left[\sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,+} \overline{\mathbf{Q}_{an_1-k_1, an_2-k_2}^{h,i,-,-}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,-} \overline{\mathbf{Q}_{an_1-k_1, an_2-k_2}^{h,i,-,+}} \right. \\ &\quad \left. + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,+} \overline{\mathbf{Q}_{an_1-k_1, an_2-k_2}^{h,i,+,-}} + \sum_{k_1, k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \overline{\mathbf{Q}_{an_1-k_1, an_2-k_2}^{h,i,+,+}} \right]; \end{aligned}$$

其中: $h=1,2,\dots,a-1; i=1,2,3$ 。

证明: 因为 $\{\Phi(x-k, y-l), \Phi(x-k, l-y), \Phi(k-x, y-l), \Phi(k-x, l-y) : k, l \in \mathbf{Z}\}$ 是 V_0 的标准正交基, 所以就有

$$\begin{aligned} \mathbf{c}_{j,n_1,n_2}^{+,+} &= \left\langle f_{j+1}, \Phi_{j,n_1,n_2}^{+,+} \right\rangle \\ &= \sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,+} \left\langle \Phi_{j+1,n_1,n_2}^{+,+}, \Phi_{j,n_1,n_2}^{+,+} \right\rangle \\ &\quad + \sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,-} \left\langle \Phi_{j+1,n_1,n_2}^{+,-}, \Phi_{j,n_1,n_2}^{+,+} \right\rangle \\ &\quad + \sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,+} \left\langle \Phi_{j+1,n_1,n_2}^{-,+}, \Phi_{j,n_1,n_2}^{+,+} \right\rangle \\ &\quad + \sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \left\langle \Phi_{j+1,n_1,n_2}^{-,-}, \Phi_{j,n_1,n_2}^{+,+} \right\rangle, \end{aligned}$$

则根据(1)式和(20)式可以知道, $\left\langle \Phi_{j+1,n_1,n_2}^{+,+}, \Phi_{j,n_1,n_2}^{+,+} \right\rangle = \frac{1}{a^2} \overline{\mathbf{P}_{k_1-an_1,k_2-an_2}^{+,+}}$ 。同理可以证得:

$$\begin{aligned} \left\langle \Phi_{j+1,n_1,n_2}^{+,-}, \Phi_{j,n_1,n_2}^{+,+} \right\rangle &= \frac{1}{a^2} \overline{\mathbf{P}_{k_1-an_1,k_2-an_2}^{+,-}}, \\ \left\langle \Phi_{j+1,n_1,n_2}^{-,+}, \Phi_{j,n_1,n_2}^{+,+} \right\rangle &= \frac{1}{a^2} \overline{\mathbf{P}_{k_1-an_1,k_2-an_2}^{-,+}}, \\ \left\langle \Phi_{j+1,n_1,n_2}^{-,-}, \Phi_{j,n_1,n_2}^{+,+} \right\rangle &= \frac{1}{a^2} \overline{\mathbf{P}_{k_1-an_1,k_2-an_2}^{-,-}}, \end{aligned}$$

故我们就可以得到

$$\begin{aligned} \mathbf{c}_{j,n_1,n_2}^{+,+} &= \frac{1}{a^2} \left[\sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,+} \overline{\mathbf{P}_{k_1-an_1,k_2-an_2}^{+,+}} + \sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,-} \overline{\mathbf{P}_{k_1-an_1,k_2-an_2}^{+,-}} \right. \\ &\quad \left. + \sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,+} \overline{\mathbf{P}_{k_1-an_1,k_2-an_2}^{-,+}} + \sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \overline{\mathbf{P}_{k_1-an_1,k_2-an_2}^{-,-}} \right], \end{aligned}$$

其它等式同理可证。

6.2. 重构算法

通过 $f(x, y)$ 在分辨率 a_j 下的主要部分和细节部分, 来重构 $f(x, y)$ 在分辨率 a_{j+1} 下的主要部分, 也即重构算法是分解算法的逆过程, 那么要实现的目标就是: 已知 $\mathbf{c}_{j,k_1,k_2}^{+,+}, \mathbf{c}_{j,k_1,k_2}^{+,-}, \mathbf{c}_{j,k_1,k_2}^{-,+}, \mathbf{c}_{j,k_1,k_2}^{-,-}$ 和

$\mathbf{d}_{j,k_1,k_2}^{+,+}, \mathbf{d}_{j,k_1,k_2}^{+,-}, \mathbf{d}_{j,k_1,k_2}^{-,+}, \mathbf{d}_{j,k_1,k_2}^{-,-}$ 求 $\mathbf{c}_{j+1,k_1,k_2}^{+,+}, \mathbf{c}_{j+1,k_1,k_2}^{+,-}, \mathbf{c}_{j+1,k_1,k_2}^{-,+}, \mathbf{c}_{j+1,k_1,k_2}^{-,-}$ 。

定理 12: 若 $f_{j+1}(x, y) = \sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,+} \Phi_{j+1,k_1,k_2}^{+,+} + \sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{+,-} \Phi_{j+1,k_1,k_2}^{+,-} + \sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,+} \Phi_{j+1,k_1,k_2}^{-,+} + \sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \Phi_{j+1,k_1,k_2}^{-,-}$

并且由(1)式和(17)式, 我们可以得到下列重构公式

$$\begin{aligned} \mathbf{c}_{j+1,n_1,n_2}^{+,+} &= \frac{1}{a^2} \left[\sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{+,+} \mathbf{P}_{n_1-ak_1,n_2-ak_2}^{+,+} + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{+,-} \mathbf{P}_{n_1-ak_1,n_2-ak_2}^{+,-} \right. \\ &\quad + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{-,+} \mathbf{P}_{n_1-ak_1,n_2-ak_2}^{-,+} + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{-,-} \mathbf{P}_{n_1-ak_1,n_2-ak_2}^{-,-} \\ &\quad + \sum_{h=1}^{a-1} \sum_{r=1}^3 \left(\sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,+,*} \mathbf{Q}_{n_1-ak_1,n_2-ak_2}^{h,i,+,*} + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,*} \mathbf{Q}_{n_1-ak_1,n_2-ak_2}^{h,i,-,*} \right. \\ &\quad \left. + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,+} \mathbf{Q}_{n_1-ak_1,n_2-ak_2}^{h,i,-,+} + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,-} \mathbf{Q}_{n_1-ak_1,n_2-ak_2}^{h,i,-,-} \right); \end{aligned}$$

$$\begin{aligned}
\mathbf{c}_{j+1,n_1,n_2}^{+,+} &= \frac{1}{a^2} \left[\sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{+,+} \mathbf{P}_{n_1-ak_1,ak_2-n_2}^{+,+} + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{+,-} \mathbf{P}_{n_1-ak_1,ak_2-n_2}^{+,-} \right. \\
&\quad + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{-,+} \mathbf{P}_{n_1-ak_1,ak_2-n_2}^{-,+} + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{-,-} \mathbf{P}_{n_1-ak_1,ak_2-n_2}^{-,-} \\
&\quad + \sum_{h=1}^{a-1} \sum_{r=1}^3 \left(\sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,+,+} \mathbf{Q}_{n_1-ak_1,ak_2-n_2}^{h,i,+,-} + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,+,-} \mathbf{Q}_{n_1-ak_1,ak_2-n_2}^{h,i,+,+} \right. \\
&\quad \left. \left. + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,+} \mathbf{Q}_{n_1-ak_1,ak_2-n_2}^{h,i,-,-} + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,-} \mathbf{Q}_{n_1-ak_1,ak_2-n_2}^{h,i,-,+} \right) \right]; \\
\mathbf{c}_{j+1,n_1,n_2}^{-,+} &= \frac{1}{a^2} \left[\sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{+,+} \mathbf{P}_{ak_1-n_1,n_2-ak_2}^{+,+} + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{+,-} \mathbf{P}_{ak_1-n_1,n_2-ak_2}^{+,-} \right. \\
&\quad + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{-,+} \mathbf{P}_{ak_1-n_1,n_2-ak_2}^{-,+} + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{-,-} \mathbf{P}_{ak_1-n_1,n_2-ak_2}^{-,-} \\
&\quad + \sum_{h=1}^{a-1} \sum_{r=1}^3 \left(\sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,+,+} \mathbf{Q}_{ak_1-n_1,n_2-ak_2}^{h,i,-,+} + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,+,-} \mathbf{Q}_{ak_1-n_1,n_2-ak_2}^{h,i,-,-} \right. \\
&\quad \left. \left. + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,+} \mathbf{Q}_{ak_1-n_1,n_2-ak_2}^{h,i,-,-} + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,-} \mathbf{Q}_{ak_1-n_1,n_2-ak_2}^{h,i,-,+} \right) \right]; \\
\mathbf{c}_{j+1,n_1,n_2}^{-,-} &= \frac{1}{a^2} \left[\sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{+,+} \mathbf{P}_{ak_1-n_1,ak_2-n_2}^{-,-} + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{+,-} \mathbf{P}_{ak_1-n_1,ak_2-n_2}^{-,+} \right. \\
&\quad + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{-,+} \mathbf{P}_{ak_1-n_1,ak_2-n_2}^{+,-} + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{-,-} \mathbf{P}_{ak_1-n_1,ak_2-n_2}^{+,-} \\
&\quad + \sum_{h=1}^{a-1} \sum_{r=1}^3 \left(\sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,+,+} \mathbf{Q}_{ak_1-n_1,ak_2-n_2}^{h,i,-,-} + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,+,-} \mathbf{Q}_{ak_1-n_1,ak_2-n_2}^{h,i,-,+} \right. \\
&\quad \left. \left. + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,+} \mathbf{Q}_{ak_1-n_1,ak_2-n_2}^{h,i,-,-} + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,-} \mathbf{Q}_{ak_1-n_1,ak_2-n_2}^{h,i,-,+} \right) \right].
\end{aligned}$$

证明：由于

$$\begin{aligned}
\mathbf{c}_{j+1,n_1,n_2}^{+,+} &= \langle f_{j+1}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle \\
&= \sum_{k_1,k_2} \mathbf{c}_{j,k_1,k_2}^{+,+} \langle \Phi_{j,n_1,n_2}^{+,+}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle + \sum_{k_1,k_2} \mathbf{c}_{j,k_1,k_2}^{+,-} \langle \Phi_{j,n_1,n_2}^{+,-}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle \\
&\quad + \sum_{k_1,k_2} \mathbf{c}_{j,k_1,k_2}^{-,+} \langle \Phi_{j,n_1,n_2}^{-,+}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle + \sum_{k_1,k_2} \mathbf{c}_{j+1,k_1,k_2}^{-,-} \langle \Phi_{j,n_1,n_2}^{-,-}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle \\
&\quad + \sum_{h=1}^{a-1} \sum_{r=1}^3 \left[\sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,+,+} \langle \Psi_{j,k_1,k_2}^{h,i,+,+}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,+,-} \langle \Psi_{j,k_1,k_2}^{h,i,+,-}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle \right. \\
&\quad \left. + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,+} \langle \Psi_{j,k_1,k_2}^{h,i,-,+}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,-} \langle \Psi_{j,k_1,k_2}^{h,i,-,-}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle \right],
\end{aligned}$$

而且 $\langle \Phi_{j,n_1,n_2}^{+,+}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle = \frac{1}{a^2} \mathbf{P}_{n_1-ak_1,n_2-ak_2}^{+,+}$ ，类似可得

$$\langle \Phi_{j,n_1,n_2}^{+,-}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle = \frac{1}{a^2} \mathbf{P}_{n_1-ak_1,n_2-ak_2}^{+,-};$$

$$\langle \Phi_{j,n_1,n_2}^{-,+}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle = \frac{1}{a^2} \mathbf{P}_{n_1-ak_1,n_2-ak_2}^{-,+};$$

$$\langle \Phi_{j,n_1,n_2}^{-,-}, \Phi_{j+1,n_1,n_2}^{+,+} \rangle = \frac{1}{a^2} \mathbf{P}_{n_1-ak_1,n_2-ak_2}^{-,-}.$$

故我们可以证得

$$\begin{aligned} \mathbf{c}_{j+1,n_1,n_2}^{+,+} &= \frac{1}{a^2} \left[\sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{+,+} \mathbf{P}_{n_1-ak_1,n_2-ak_2}^{+,+} + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{+,-} \mathbf{P}_{n_1-ak_1,n_2-ak_2}^{+,-} \right. \\ &\quad + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{-,+} \mathbf{P}_{n_1-ak_1,n_2-ak_2}^{-,+} + \sum_{k_1,k_2} \mathbf{c}_{j,n_1,n_2}^{-,-} \mathbf{P}_{n_1-ak_1,n_2-ak_2}^{-,-} \\ &\quad + \sum_{h=1}^{a-1} \sum_{r=1}^3 \left(\sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,+,+} \mathbf{Q}_{n_1-ak_1,n_2-ak_2}^{h,i,+,+} + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,+,-} \mathbf{Q}_{n_1-ak_1,n_2-ak_2}^{h,i,+,-} \right. \\ &\quad \left. \left. + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,+} \mathbf{Q}_{n_1-ak_1,n_2-ak_2}^{h,i,-,+} + \sum_{k_1,k_2} \mathbf{d}_{j,n_1,n_2}^{h,i,-,-} \mathbf{Q}_{n_1-ak_1,n_2-ak_2}^{h,i,-,-} \right) \right]; \end{aligned}$$

其它等式同理可证。

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