

带一个自相容源的(3 + 1)-维KP-I方程的广义Dromion结构

苏丹

湛江幼儿师范专科学校, 广东 湛江

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摘要

本文利用Hirota双线性方法构造了具有一个自相容源的(3 + 1)-维KP-I方程(KPIESCS)的指数局部化解。我们得到了该方程广义dromion型解和多dromion解。

关键词

指数局部化解, 带自相容源的(3 + 1)-维KP-I方程, 双线性方法

Generalized Dromion Structures of the (3 + 1)-Dimensional Kadomtsev-Petviashvili I Equation with a Self-Consistent Source

Dan Su

Department of Mathematics of Zhanjiang Preschool Education College, Zhanjiang Guangdong

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Abstract

Exponentially localized solutions to the (3 + 1)-dimensional Kadomtsev-Petviashvili I equation with a self-consistent source (KPIESCS) are constructed by the Hirota bilinear method. The generalized dromion type solutions and multi-dromion solutions are obtained.

Keywords

Exponentially Localized Solutions, (3 + 1)-Dimensional Kadomtsev-Petviashvili I Equation with a

Self-Consistent Source, Hirota Bilinear Method

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1. 引言

自从 Zabusky 和 Kruskal 在非线性波的数值研究中首次提出“孤子”一词后,孤子理论引起了人们的广泛关注[1]。孤子理论作为非线性科学的一个分支,在数学和物理中有着广泛的应用[2] [3]。此外,具有自相容源的方程在物理学中具有重要的实际意义,因为它们可以反映不同波之间的相互作用[4] [5] [6] [7]。目前,求解这些方程的方法主要有两种。一种是基于 Lax 对的分析方法,如达布变换方法[8] [9],贝克隆变换方法[10] [11]和逆散射方法[12] [13] [14]。另一种广泛使用的方法是 Hirota 双线性方法,它是一种代数方法而不是解析方法[15] [16]。

对于高维可积模型,最重要的特性之一是发现了称为 dromion 的指数局部化结构[17]。通常, dromion 由两个或多个非平行线 ghost 孤子驱动[18] [19]。在具有奇偶时间对称势的(2 + 1)维 KdV 方程、(3 + 1)维条件可积系统和(2 + 1)维非线性薛定谔方程中,得到了 dromion 结构[20] [21] [22]。此外,在 Mel'nikov 方程的情况下,得到了更一般的具有空间变化振幅的 dromion 型解以及包含的多 dromion 解[23]。

在本文中,我们将重点讨论如下形式的带一个自相容源的(3 + 1)维 Kadomtsev-Petviashvili 方程 (KPIESCS)广义形式的 dromion 结构

$$\begin{cases} \left(u_t + 6uu_x + u_{xxx} + 8\kappa|\phi|_x^2\right)_x - u_{yy} + u_{zz} = 0, \\ i\phi_y = 2\phi_{xx} + 2u\phi, \\ i\phi_z = \phi_{xx} + u\phi. \end{cases} \quad (1)$$

其中, u 是长波振幅, ϕ 是复的短波包, κ 满足条件 $\kappa^2 = 1$ 。文献[24]讨论了该方程一般有理解的显式表示。

2. 方程(1)的局部解

通过因变量转换 $u = 2(\ln f)_{xx}$, $\phi = g/f$, 方程(1)被转换成双线性方程

$$\begin{cases} \left(D_x D_t + D_x^4 - D_y^2 + D_z^2\right) f \cdot f + 8\kappa g \cdot \bar{g} = 0, \\ \left(iD_y - 2D_x^2\right) g \cdot f = 0, \\ \left(iD_z - D_x^2\right) g \cdot f = 0. \end{cases} \quad (2)$$

以 ε 幂级数的形式展开 f, g , 如下所示

$$g = \varepsilon g^{(1)} + \varepsilon^3 g^{(3)} + \dots, \quad f = 1 + \varepsilon^2 f^{(2)} + \varepsilon^4 f^{(4)} + \dots, \quad (3)$$

将(3)代入(2)可以得到一组线性方程

$$\begin{cases} O(\varepsilon): ig_z^{(1)} = g_{xx}^{(1)}, \quad ig_y^{(1)} = 2g_{xx}^{(1)}, \\ O(\varepsilon^2): f_{xxx}^{(2)} + f_{xt}^{(2)} - f_{yy}^{(2)} + f_{zz}^{(2)} = 4\kappa |g^{(1)}|^2, \\ \vdots \end{cases} \quad (4)$$

为了得到孤立子解, 令

$$g^{(1)} = \sum_{j=1}^N \exp(\psi_j), \psi_j = l_j x + m_j y + n_j z + \omega_j t + \psi_j^{(0)}, in_j = l_j^2, m_j = 2n_j, \quad (5)$$

其中 $l_j, m_j, \omega_j, \psi_j^{(0)}$ 是复的待定系数。当 $N=1$ 时我们得到

$$f^{(2)} = \exp(\psi_1 + \psi_1^* + 2A), \exp(2A) = \frac{\kappa}{4l_{1R}^4 + l_{1R}\omega_{1R} - 3n_{1R}^2}, \quad (6)$$

这里 $l_1 = l_{1R} + il_{1I}, m_1 = m_{1R} + im_{1I}, n_1 = n_{1R} + in_{1I}, \omega_1 = \omega_{1R} + i\omega_{1I}$, $g^{(2j-1)} = f^{(2j)} = 0 (j \geq 2)$ 。此时我们得到孤立子解

$$\begin{cases} u = 2l_{1R}^2 \operatorname{sech}^2(\psi_{1R} + A), \\ \phi = \sqrt{\frac{4l_{1R}^4 + l_{1R}\omega_{1R} - 12l_{1R}^2 l_{1I}^2}{4\kappa}} \operatorname{sech}(\psi_{1R} + A) e^{i\psi_{1I}}, \end{cases} \quad (7)$$

其中 $\psi_{1R} = l_{1R}x + m_{1R}y + 2l_{1R}l_{1I}z + \omega_{1R}t + \psi_{1R}^{(0)}, \psi_{1I} = l_{1I}x + m_{1I}y - (l_{1R}^2 - l_{1I}^2)z + \omega_{1I}t + \psi_{1I}^{(0)}$ 。

特别地, 为了得到类似文献[19]中的(1,1)-dromion 解, 我们取

$$f = 1 + e^{\psi_1 + \psi_1^*} + e^{\psi_2 + \psi_2^*} + Ke^{\psi_1 + \psi_1^* + \psi_2 + \psi_2^*}, g = \rho e^{\psi_1 + \psi_2}, \quad (8)$$

其中

$$\psi_1 = px + my + nz, \quad \psi_2 = qt, \quad (9)$$

并且 $K > 0$ 是一个待定实数, p, m, n, q 是待定复系数。将(8)式代入(2)式中的第一个方程可以得到当 $3n_R^2 = 4p_R^4$ 时满足

$$\kappa |\rho|^2 = p_R q_R (K - 1), \quad (10)$$

然后再将(8)和(10)代入(2)式中的第二个方程得到 $m = 2n, n = -ip^2, p_R^2 = 3p_I^2$ 。

因此, 我们得到如下形式的指数衰减解

$$\begin{cases} u = \frac{8p_R^2 (1 + e^{\psi_2 + \psi_2^*}) (e^{\psi_1 + \psi_1^*} + Ke^{\psi_1 + \psi_1^* + \psi_2 + \psi_2^*})}{(1 + e^{\psi_1 + \psi_1^*} + e^{\psi_2 + \psi_2^*} + Ke^{\psi_1 + \psi_1^* + \psi_2 + \psi_2^*})^2}, \\ \phi = \frac{\rho e^{\psi_1 + \psi_2}}{1 + e^{\psi_1 + \psi_1^*} + e^{\psi_2 + \psi_2^*} + Ke^{\psi_1 + \psi_1^* + \psi_2 + \psi_2^*}}, \end{cases} \quad (11)$$

此外, 可以看到(4)式中的第一个方程只和自变量 x, y, z 有关, 因此可以引入一些关于自变量 t 的任意函数来寻找更一般形式的解。例如, 选择

$$g^{(1)} = \sum_{j=1}^N \exp(\psi_j), \psi_j = l_j x + m_j y + n_j z + a_j(t) + \psi_j^{(0)}, in_j = l_j^2, m_j = 2n_j, \quad (12)$$

或者

$$g^{(1)} = \sum_{j=1}^N a_j(t) \exp(\psi_j), \psi_j = l_j x + m_j y + n_j z + \psi_j^{(0)}, in_j = l_j^2, m_j = 2n_j. \quad (13)$$

为了说明此种情况, 不妨假设

$$g^{(1)} = a(t) e^{\psi_1}, \psi_1 = l_1 x + m_1 y + n_1 z, \quad (14)$$

这里 $a(t)$ 是一个复函数, 复系数 l_1, n_1, m_1 满足色散关系 $l_1^2 = in_1, m_1 = 2n_1$ 。将(14)代入(4)式第二个方程, 我们得到

$$f^{(2)} = b(t)e^{i\psi_1 + \psi_1^*}, \tag{15}$$

其中 $b(t)$ 是一个满足如下关系的实函数

$$8l_{1R}^4 b(t) + l_{1R} b'(t) - 6n_{1R}^2 b(t) = 2\kappa |a(t)|^2. \tag{16}$$

于是我们得到方程(1)如下形式的解

$$\begin{cases} u = 2l_{1R}^2 \operatorname{sech}^2 \left[\psi_{1R} + \frac{1}{2} \ln b(t) \right], \\ \phi = \frac{a(t)}{2\sqrt{b(t)}} e^{i\psi_{1I}} \operatorname{sech} \left[\psi_{1I} + \frac{1}{2} \ln b(t) \right], \end{cases} \tag{17}$$

其中 ψ_{1R}, ψ_{1I} 分别是 ψ_1 的实部和虚部。显然, 此时 u 是一个曲线孤子, 自相容源项 ϕ 拥有丰富的结构。例如, 如果选择

$$\frac{a(t)}{\sqrt{b(t)}} = 2 \operatorname{sech}(c_0 + c_1 t), \tag{18}$$

我们可以从(16)式中求得

$$b(t) = \exp \left(\frac{8\kappa \tanh(c_0 + c_1 t) + (6n_{1R}^2 - 8l_{1R}^4)t}{l_{1R}} \right), \tag{19}$$

于是可以得到

$$\phi = e^{i\psi_{1I}} \operatorname{sech}(c_0 + c_1 t) \operatorname{sech} \left[l_{1R}(x + 4l_{1I}y + 2l_{1I}z) + \frac{1}{2l_{1R}} (8\kappa \tanh(c_0 + c_1 t) + (6n_{1R}^2 - 8l_{1R}^4)t) \right]. \tag{20}$$

这就是一个 dromion 型解。

如果选择

$$\frac{a(t)}{\sqrt{b(t)}} = \frac{2}{(t+t_0)^2 + 1}, \tag{21}$$

我们就得到一个代数衰减的局部解

$$\phi = \frac{e^{i\psi_{1I}}}{(t+t_0)^2 + 1} \operatorname{sech} \left\{ l_{1R}(x + 4l_{1I}y + 2l_{1I}z) + \frac{1}{2l_{1R}} \left[(6n_{1R}^2 - 8l_{1R}^4)t + 8\kappa \int \frac{dt}{[(t+t_0)^2 + 1]^2} \right] \right\}, \tag{22}$$

这个解沿着 t 方向衰减的速度要比解(20)慢很多。

通过扩展上述步骤, 我们可以构造广义形式的局部解。实际上, 可以得到如下形式的多 dromion 解

$$\phi_N = \left[\frac{\sum_{j=1}^M a_j(t)}{2\sqrt{b(t)}} \right] e^{i\psi_{1I}} \operatorname{sech} \left[\psi_{1R} + \frac{1}{2} \ln b(t) \right]. \tag{23}$$

这里 $a_j(t)$, $j=1,2,\dots,N$ 是关于自变量 t 的任意函数且满足

$$8l_{1R}^4 b(t) + l_{1R} b'(t) - 6n_{1R}^2 b(t) = 2\kappa \sum_{p=1}^M \sum_{q=1}^M a_p(t) a_q^*(t), \quad (24)$$

为了说明这种解, 我们取 $M=2$ 为例。令

$$\frac{a_1(t)}{\sqrt{b(t)}} = 2\operatorname{sech}(t + \eta_1), \quad \frac{a_2(t)}{\sqrt{b(t)}} = 2\operatorname{sech}(t + \eta_2), \quad (25)$$

求解式(24)得到

$$b(t) = \exp \left[\frac{\left((6n_{1R}^2 - 8l_{1R}^4)t + 8\kappa \left(\tanh(t + \eta_1) + \tanh(t + \eta_2) + 2 \int \operatorname{sech}(t + \eta_1) \operatorname{sech}(t + \eta_2) dt \right) \right)}{l_{1R}} \right], \quad (26)$$

此时就可以到一个高阶 dromion 解

$$\begin{aligned} \phi_2 = e^{i\psi_{11}} & \left[\operatorname{sech}(t + \eta_1) + \operatorname{sech}(t + \eta_2) \right] \operatorname{sech} \left[l_{1R} (x + 4l_{11}y + 2l_{11}z) + \frac{1}{2l_{1R}} \left((6n_{1R}^2 - 8l_{1R}^4)t \right. \right. \\ & \left. \left. + 8\kappa \left(\tanh(t + \eta_1) + \tanh(t + \eta_2) + 2 \int \operatorname{sech}(t + \eta_1) \operatorname{sech}(t + \eta_2) dt \right) \right) \right]. \end{aligned} \quad (27)$$

3. 总结

本文中, 我们基于 Hirota 双线性方法找到了 $(3+1)$ 维 KPIESCS 的指数局部化解。我们特别构造了局域 dromion 解和诱导 dromion 解。

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