

高阶分数阶微分方程边值问题解的存在唯一性

王张驰

兰州理工大学, 理学院, 甘肃 兰州

收稿日期: 2023年5月21日; 录用日期: 2023年6月22日; 发布日期: 2023年6月30日

摘要

研究了具有混合单调非线性项的Riemann-Liouville型高阶分数阶微分方程边值问题。利用Green函数的性质以及混合单调算子的不动点定理证明了该边值问题解的存在唯一性, 并给出一个实例验证了结论的正确性。

关键词

分数阶微分方程, 边值问题, 混合单调算子, 存在唯一性

Existence and Uniqueness of Solutions to Boundary Value Problems for Higher-Order Fractional Differential Equations

Zhangchi Wang

School of Science, Lanzhou University of Technology, Lanzhou Gansu

Received: May 21st, 2023; accepted: Jun. 22nd, 2023; published: Jun. 30th, 2023

Abstract

The boundary value problem of Riemann-Liouville higher order fractional differential

equations with mixed monotone nonlinear terms is studied. By using the properties of Green's function and the fixed point theorem of mixed monotone operators, the existence and uniqueness of the solution of the boundary value problem are proved, and an example is given to verify the correctness of the conclusion.

Keywords

Fractional Differential Equation, Boundary Value Problem, Mixed Monotone Operator, Existence and Uniqueness

Copyright © 2023 by author(s) and Hans Publishers Inc.

This work is licensed under the Creative Commons Attribution International License (CC BY 4.0).

<http://creativecommons.org/licenses/by/4.0/>



Open Access

1. 引言

在过去的几十年中,分数阶微分方程因其在电化学、粘弹性、电磁学、多孔介质、控制等各个领域的应用而变得越来越重要. 有关详细信息, 请参阅 [1-12] 及其中的参考文献. 近年来, 关于分数阶微分方程的研究受到了许多学者的关注, 如: 不同边值条件下解的存在唯一性, 正解的存在唯一性, 其主要研究方法包括锥上不动点定理, 混合单调算子上的不动点定理等.

文献 [13] 应用混合单调算子的不动点定理研究了分数阶微分方程边值问题

$$\begin{cases} D_{0+}^{\alpha} u(t) + q(t)f(u, u', \dots, u^{(n-2)}) = 0, & 0 < t < 1, & n-1 < \alpha \leq n, \\ u(0) = u'(0) = \dots = u^{(n-2)}(0) = u^{(n-2)}(1) = 0 \end{cases} \quad (1)$$

正解的存在唯一性, 其中 D_{0+}^{α} 是标准的Riemann-Liouville 型分数阶微分导数, $n \geq 2$, $n \in \mathbb{N}$, 函数 f 和 q 满足如下特性:

(C₁) $f(x_1, x_2, \dots, x_{n-1}) = g(x_1, x_2, \dots, x_{n-1}) + h(x_1, x_2, \dots, x_{n-1})$, 其中 $g : [0, +\infty) \times R^{n-2} \rightarrow [0, +\infty)$ 是连续的, $h : (0, +\infty) \times (R \setminus \{0\})^{n-2} \rightarrow (0, +\infty)$ 是连续的.

(C₂) g 在 $x_i > 0$, $i = 1, 2, \dots, n-1$ 时是非减的; 此外, h 在 $x_i > 0$, $i = 1, 2, \dots, n-1$ 是非增的.

(C₃) 存在 $\beta \in (0, 1)$ 使得对于 $x_i > 0$, $i = 1, 2, \dots, n-1$ 有

$$\begin{aligned} g(tx_1, \dots, tx_{n-1}) &\geq t^{\beta} g(x_1, \dots, x_{n-1}), & t \in (0, 1), \\ h(t^{-1}x_1, \dots, t^{-1}x_{n-1}) &\geq t^{\beta} h(x_1, \dots, x_{n-1}), & t \in (0, 1). \end{aligned}$$

(C₄) $t^r q : [0, 1] \rightarrow [0, +\infty)$ 是连续的且 $\int_0^1 q(s)s^{-\beta(\alpha-1)} ds < +\infty$, $0 \leq r < 1$.

文献 [14] 研究了以下分数阶微分方程边值问题

$$\begin{cases} -D_{0+}^{\alpha} u(t) = f(t, u(t), u(t)) + g(t, u(t), u(t)) - b, & t \in (0, 1), n-1 < \alpha \leq n, \\ u^{(i)}(0) = 0, & i = 0, 1, \dots, n-2, \\ D_{0+}^{\beta} u(1) = 0, & 1 \leq \beta \leq n-2 \end{cases} \quad (2)$$

解的存在唯一性, 其中 D_{0+}^{α} , D_{0+}^{β} 是标准的Riemann-Liouville 型分数阶微分导数, $n \geq 3$, $b > 0$ 是常数, $f, g : [0, 1] \times (-\infty, +\infty) \times (-\infty, +\infty) \rightarrow (-\infty, +\infty)$ 是连续函数. 问题(2) 包括著名的弹性梁方程和文献 [15, 16] 中考虑的分阶问题.

最近, 自Guo 和Lakshmikantham [17] 引入混合单调算子以来, 许多学者都研究了Banach 空间中各种类型的混合单调算子, 并构造了许多相关的定理. 在文献 [18] 中, Bhaskar 和Lakshikantham 在半序度量空间中研究了混合单调算子的一些耦合不动点定理. 在文献 [19] 中, Li 和Zhao 考虑了一类 $\tau - \phi$ 的混合单调算子. 此外, 具有扰动的混合单调算子已被广泛研究. 在 [20] 中, Liu 等人考虑了算子方程:

$$A(x, x) + B(x, x) = x$$

在半序Banach 空间上正解的存在唯一性, 其中 A 和 B 是两个混合单调算子, 此外, 作者还给出了该算子非线性分数阶微分方程中应用.

受上述工作的启发, 本文将运用文献 [14] 中混合单调算子的不动点定理研究如下具有混合单调非线性项的高阶分数阶微分方程边值问题

$$\begin{cases} D_{0+}^{\alpha} u(t) + q(t)f(u(t), u'(t), \dots, u^{(n-2)}(t)) - b = 0, & t \in [0, 1], \\ u(0) = u'(0) = \dots = u^{(n-2)}(0) = u^{(n-2)}(1) = 0 \end{cases} \quad (3)$$

解的存在唯一性, 其中 D_{0+}^{α} 是标准的Riemann-Liouville 型分数阶微分导数, $b > 0$ 是一个常数, $n-1 < \alpha \leq n$, $n \geq 2$, f 是一个非线性函数, $q \in C[0, 1]$ 满足 $q(t) \geq 0$, $q(t) \not\equiv 0$.

2. 预备知识

方便起见, 首先给出一些必要的定义和引理, 为后续的研究工作提供数学工具.

定义 2.1 [2, 4] 函数 $y \in C[0, 1]$ 的 $\alpha > 0$ 阶Riemann-Liouville 分数积分定义为

$$I_{0+}^{\alpha} y(t) = \frac{1}{\Gamma(\alpha)} \int_0^t \frac{y(s)}{(t-s)^{1-\alpha}} ds.$$

定义 2.2 [2, 4] 函数 $y \in C[0, 1]$ 的 $\alpha > 0$ 阶Riemann-Liouville 分数阶导数定义为

$$D_{0+}^{\alpha} y(t) = \frac{1}{\Gamma(n-\alpha)} \left(\frac{d}{dt} \right)^n \int_0^t \frac{y(s)}{(t-s)^{\alpha-n-1}} ds,$$

其中 $n = [\alpha] + 1$.

引理 2.1 [13] 令 $y \in C[0, 1]$, 那么边值问题

$$\begin{cases} D_{0+}^{\alpha-n+2}x(t) + y(t) = 0, 0 \leq t \leq 1, n - 1 < \alpha \leq n, n \geq 2, \\ x(0) = x(1) = 0 \end{cases} \quad (4)$$

有唯一解

$$x(t) = \int_0^1 G(t, s)y(s)ds,$$

其中

$$G(t, s) = \begin{cases} \frac{(t(1-s))^{\alpha-n+1} - (t-s)^{\alpha-n+1}}{\Gamma(\alpha-n+2)}, & 0 \leq s \leq t \leq 1, \\ \frac{(t(1-s))^{\alpha-n+1}}{\Gamma(\alpha-n+2)}, & 0 \leq t \leq s \leq 1. \end{cases} \quad (5)$$

引理 2.2 [13] 定义(5) 中的函数 $G(t, s)$ 满足如下条件:

- (1) $G(t, s) \geq 0, G(t, s) \leq t^{\alpha-n+1}/\Gamma(\alpha - n + 2), G(t, s) \leq G(s, s), 0 \leq t, s \leq 1;$
- (2) 存在一个正函数 $\rho \in C(0, 1)$ 使得 $\min_{\gamma \leq t \leq \delta} G(t, s) \geq \rho(s)G(s, s), s \in (0, 1),$ 其中 $0 < \gamma < \delta < 1.$

引理 2.3 令 $u(t) = I_{0+}^{n-2}x(t), x(t) \in C[0, 1],$ 那么 $D_{0+}^{n-2}u(t) = x(t).$ 问题(3) 可以转变成如下问题(6):

$$\begin{cases} D_{0+}^{\alpha-n+2}x(t) + q(t)f(I_{0+}^{n-2}x(t), I_{0+}^{n-3}x(t), \dots, x(t)) - b = 0, 0 \leq t \leq 1, n - 1 < \alpha \leq n, n \geq 2, \\ x(0) = x(1) = 0. \end{cases} \quad (6)$$

如果 $x \in C[0, 1]$ 是问题(6) 的解, 那么 $u(t) = I_{0+}^{n-2}x(t)$ 是问题(3) 的解.

证. 该证明与文献 [13] 中引理2.7 类似, 此处省略. □

本文中, E 是赋范的实Banach 空间, θ 是 E 中的零元. 一个非空闭凸集 $P \in E$ 如果满足(1) $x \in P, \lambda \geq 0 \Rightarrow \lambda x \in P;$ (2) $x \in P, -x \in P \Rightarrow x = \theta,$ 则称 P 是 E 上的一个锥. E 中的半序关系为 $x \lesssim y$ 当且仅当 $y - x \in P.$ 此外, 如果存在一个常数 $N > 0$ 使得对所有的 $x, y \in E, \theta \lesssim x \lesssim y$ 有 $\|x\| \leq N\|y\|,$ 则称 P 是一个正规锥, 其中最小的 N 被称为是 P 的正规常数. 给定 $h > \theta$ (i.e., $\theta \lesssim h$ 且 $h \neq \theta$), 我们定义集合 C_h 为

$$C_h = \{x \in E \mid \text{存在 } \lambda > 0 \text{ 和 } \mu > 0 \text{ 使得 } \lambda h \lesssim x \lesssim \mu h\}.$$

设 $e \in P,$ 且 $\theta \lesssim e \lesssim h.$ 定义

$$C_{h,e} = \{x \in E \mid x + e \in C_h\}.$$

定义 2.3 [21] $A : C_{h,e} \times C_{h,e} \rightarrow E,$ 如果 $A(x, y)$ 关于 x 非减关于 y 非增, 则称 A 是混合单调的, 即如果 $x_i, y_i \in C_{h,e} (i = 1, 2), x_1 \leq x_2, y_1 \geq y_2,$ 则 $A(x_1, y_1) \leq A(x_2, y_2).$

引理 2.4 [14] 设 $A, B : C_{h,e} \times C_{h,e} \rightarrow E$ 是两个混合单调算子且满足如下条件:

(i) 对于所有的 $t \in (0, 1)$, 存在 $\psi(t) \in (t, 1)$ 使得

$$A(tx + (t-1)e, t^{-1}y + (t^{-1}-1)e) \geq \psi(t)A(x, y) + (\psi(t)-1)e, \forall x, y \in C_{h,e};$$

(ii) 对于所有的 $t \in (0, 1)$ 和 $x, y \in C_{h,e}$,

$$B(tx + (t-1)e, t^{-1}y + (t^{-1}-1)e) \geq tB(x, y) + (t-1)e;$$

(iii) $A(h, h) \in C_{h,e}$ 且 $B(h, h) \in C_{h,e}$;

(iv) 存在一个常数 $\delta > 0$, 使得对于所有的 $x, y \in C_{h,e}$, 有

$$A(x, y) \geq \delta B(x, y) + (\delta - 1)e.$$

那么算子方程 $A(x, x) + B(x, x) + e = x$ 在 $C_{h,e}$ 上有唯一解 x^* , 并且对于任何初值 $x_0, y_0 \in C_{h,e}$, 构造序列

$$\begin{aligned} x_n &= A(x_{n-1}, y_{n-1}) + B(x_{n-1}, y_{n-1}) + e, \\ y_n &= A(y_{n-1}, x_{n-1}) + B(y_{n-1}, x_{n-1}) + e, \quad n = 1, 2, \dots, \end{aligned}$$

当 $n \rightarrow \infty$ 时, 在 E 中有 $x_n \rightarrow x^*$, $y_n \rightarrow x^*$.

3. 主要结果

方便起见, 我们定义如下符号.

对于 $t \in [0, 1]$,

$$\begin{aligned} e(t) &= \frac{b}{\Gamma(\alpha - n + 3)} (t^{\alpha-n+1} - t^{\alpha-n+2}), \\ E^* &= \max\{I_{0+}^{n-2}e(t), I_{0+}^{n-3}e(t), \dots, e(t)\}. \end{aligned}$$

定理 3.1 如果以下条件成立:

(H₁) 对于任意的 $x_i \in [-E^*, +\infty)$ ($i = 0, 1, 2, \dots, n-2$), 有 $f(x_0, x_1, \dots, x_{n-2}) = g(x_0, x_1, \dots, x_{n-2}, x_0,$

$x_1, \dots, x_{n-2}) + \phi(x_0, x_1, \dots, x_{n-2}, x_0, x_1, \dots, x_{n-2})$ 其中 $g \in C([-E^*, +\infty)^{2(n-1)}, (-\infty, +\infty))$,

$\phi \in C([-E^*, +\infty)^{2(n-1)}, (-\infty, +\infty))$.

(H₂) 对于任意固定的 $y_i \in [-E^*, +\infty)$ ($i = 0, 1, 2, \dots, n-2$), $g(x_0, x_1, \dots, x_{n-2}, y_0, y_1, \dots, y_{n-2})$ 和 $\phi(x_0, x_1, \dots, x_{n-2}, y_0, y_1, \dots, y_{n-2})$ 在 $x_i \in [-E^*, +\infty)$ 非减; 对于任意固定的 $x_i \in [-E^*, +\infty)$

($i = 0, 1, 2, \dots, n-2$), $g(x_0, x_1, \dots, x_{n-2}, y_0, y_1, \dots, y_{n-2})$ 和 $\phi(x_0, x_1, \dots, x_{n-2}, y_0, y_1, \dots, y_{n-2})$ 在 $y_i \in [-E^*, +\infty)$ 非增.

(H₃) 对于任意的 $\tau \in (0, 1)$, 存在 $\varphi(\tau) \in (\tau, 1)$ 使得对于所有的 $x_i, y_i \in [-E^*, +\infty)$ ($i = 0, 1, \dots, n-$

2), 有

$$\begin{aligned}
 &g(\tau x_0 + (\tau - 1)\rho_0, \tau x_1 + (\tau - 1)\rho_0, \dots, \tau x_{n-2} + (\tau - 1)\rho_0, \tau^{-1}y_0 + (\tau^{-1} - 1)\rho_0, \\
 &\tau^{-1}y_1 + (\tau^{-1} - 1)\rho_0, \dots, \tau^{-1}y_{n-2} + (\tau^{-1} - 1)\rho_0) \geq \varphi(\tau)g(x_0, x_1, \dots, x_{n-2}, y_0, y_1, \dots, y_{n-2}), \rho_0 \in [0, E^*], \\
 &\phi(\tau x_0 + (\tau - 1)\rho_0, \tau x_1 + (\tau - 1)\rho_0, \dots, \tau x_{n-2} + (\tau - 1)\rho_0, \tau^{-1}y_0 + (\tau^{-1} - 1)\rho_0, \\
 &\tau^{-1}y_1 + (\tau^{-1} - 1)\rho_0, \dots, \tau^{-1}y_{n-2} + (\tau^{-1} - 1)\rho_0) \geq \tau h(x_0, x_1, \dots, x_{n-2}, y_0, y_1, \dots, y_{n-2}), \rho_0 \in [0, E^*].
 \end{aligned}$$

(H₄) 对于任意固定的 $x_i, y_i \in [-E^*, +\infty) (i = 0, 1, 2, \dots, n - 2)$, 存在一个常数 $\delta_0 > 0$ 使得

$$g(x_0, x_1, \dots, x_{n-2}, y_0, y_1, \dots, y_{n-2}) \geq \delta_0 \phi(x_0, x_1, \dots, x_{n-2}, y_0, y_1, \dots, y_{n-2}).$$

(H₅) 存在一个常数 $M = \frac{b}{(\alpha - n + 1)\Gamma(\alpha - n + 3)}$, 使得函数 g 和函数 ϕ 满足

$$\begin{aligned}
 &g(M, M, \dots, M, 0, 0, \dots, 0) < +\infty, \\
 &\phi(M, M, \dots, M, 0, 0, \dots, 0) < +\infty, \\
 &\phi(0, 0, \dots, 0, M, M, \dots, M) > 0.
 \end{aligned}$$

那么问题(6)在 $C_{h,e}$ 有唯一的平凡解 x^* , 其中 $h(t) = Mt^{\alpha-n+1}, t \in [0, 1]$. 此外, 可以构建以下两个序列:

$$\begin{aligned}
 \omega_n(t) &= \int_0^1 G(t, s)g(I_{0+}^{n-2}\omega_{n-1}(s), I_{0+}^{n-3}\omega_{n-1}(s), \dots, \omega_{n-1}(s), I_{0+}^{n-2}\tau_{n-1}(s), I_{0+}^{n-3}\tau_{n-1}(s), \\
 &\dots, \tau_{n-1}(s))ds + \int_0^1 G(t, s)q(s)\phi(I_{0+}^{n-2}\omega_{n-1}(s), I_{0+}^{n-3}\omega_{n-1}(s), \dots, \omega_{n-1}(s), \\
 &I_{0+}^{n-2}\tau_{n-1}(s), I_{0+}^{n-3}\tau_{n-1}(s), \dots, \tau_{n-1}(s))ds - \frac{b}{\Gamma(\alpha - n + 3)}(t^{\alpha-n+1} - t^{\alpha-n+2}), \\
 &n = 1, 2, \dots, \\
 \tau_n(t) &= \int_0^1 G(t, s)g(I_{0+}^{n-2}\tau_{n-1}(s), I_{0+}^{n-3}\tau_{n-1}(s), \dots, \tau_{n-1}(s), I_{0+}^{n-2}\omega_{n-1}(s), I_{0+}^{n-3}\omega_{n-1}(s), \\
 &\dots, \omega_{n-1}(s))ds + \int_0^1 G(t, s)q(s)\phi(I_{0+}^{n-2}\tau_{n-1}(s), I_{0+}^{n-3}\tau_{n-1}(s), \dots, \tau_{n-1}(s), \\
 &I_{0+}^{n-2}\omega_{n-1}(s), I_{0+}^{n-3}\omega_{n-1}(s), \dots, \omega_{n-1}(s))ds - \frac{b}{\Gamma(\alpha - n + 3)}(t^{\alpha-n+1} - t^{\alpha-n+2}), \\
 &n = 1, 2, \dots,
 \end{aligned}$$

对于任意给定的 $\omega_0, \tau_0 \in C_{h,e}, t \in [0, 1]$, 有 $\{\omega_n(t)\}$ 和 $\{\tau_n(t)\}$ 都一致收敛于 x^* .

证. 对于 $t \in [0, 1]$,

$$\begin{aligned}
 e(t) &= \frac{b}{\Gamma(\alpha - n + 3)}(t^{\alpha-n+1} - t^{\alpha-n+2}) \geq 0, \\
 E^* &= \max\{I_{0+}^{n-2}e(t), I_{0+}^{n-3}e(t), \dots, e(t)\}.
 \end{aligned}$$

即 $e, E^* \in P$. 此外, $e(t) \leq E^* \leq \frac{b}{(\alpha - n + 1)\Gamma(\alpha - n + 3)}t^{\alpha-n+1} = h(t), C_{h,e} = \{x \in C[0, 1] | x + e \in C_h\}$.

证明之前, 首先转换 $x(t)$. 由引理2.1 和 (H_1) , 问题(6) 的积分公式为

$$\begin{aligned}
 x(t) &= \int_0^1 G(t, s)[q(s)f(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s)) - b]ds \\
 &= \int_0^1 G(t, s)q(s)f(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s))ds - b \int_0^1 G(t, s)ds \\
 &= \int_0^1 G(t, s)q(s)[g(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s)) + \\
 &\quad \phi(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s))]ds - \frac{b(t^{\alpha-n+1} - t^{\alpha-n+2})}{\Gamma(\alpha - n + 3)} \\
 &= \int_0^1 G(t, s)q(s)g(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s))ds + \\
 &\quad \int_0^1 G(t, s)q(s)\phi(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s))ds - e(t) \\
 &= \int_0^1 G(t, s)q(s)g(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s))ds - e(t) + \\
 &\quad \int_0^1 G(t, s)q(s)\phi(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s))ds - e(t) + e(t),
 \end{aligned}$$

其中 $G(t, s)$ 在(5) 给出. 对于每个 $t \in [0, 1]$, $x, y \in C_{h,e}$, 定义如下算子:

$$\begin{aligned}
 A(x, y)(t) &= \int_0^1 G(t, s)q(s)g(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}y(s), I_{0+}^{n-3}y(s), \dots, y(s))ds - e(t), \\
 B(x, y)(t) &= \int_0^1 G(t, s)q(s)\phi(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}y(s), I_{0+}^{n-3}y(s), \dots, y(s))ds - e(t).
 \end{aligned}$$

很容易证明 x 是问题(6) 的解当且仅当 $x = A(x, x) + B(x, x) + e$. 接下来, 分四步证明 A 和 B 满足引理2.4中的条件.

(1) 首先, 证明 $A, B : C_{h,e} \times C_{h,e} \rightarrow E$ 是混合单调算子. 事实上, 对于所有的 $x_i, y_i \in C_{h,e} (i = 1, 2)$ 且 $x_1 \geq x_2, y_1 \leq y_2$, 由 (H_2) , 可得

$$\begin{aligned}
 A(x_1, y_1)(t) &= \int_0^1 G(t, s)q(s)g(I_{0+}^{n-2}x_1(s), I_{0+}^{n-3}x_1(s), \dots, x_1(s), I_{0+}^{n-2}y_1(s), I_{0+}^{n-3}y_1(s), \dots, y_1(s))ds - e(t) \\
 &\geq \int_0^1 G(t, s)q(s)g(I_{0+}^{n-2}x_2(s), I_{0+}^{n-3}x_2(s), \dots, x_2(s), I_{0+}^{n-2}y_2(s), I_{0+}^{n-3}y_2(s), \dots, y_2(s))ds - e(t) \\
 &= A(x_2, y_2)(t).
 \end{aligned}$$

即 $A(x_1, y_1) \geq A(x_2, y_2)$. 用同样的方法可以得出 $B(x_1, y_1) \geq B(x_2, y_2)$.

(2) 其次, 验证引理2.4 中的(i) 和(ii) 成立. 由 (H_3) , 对每个 $\tau \in (0, 1), t \in [0, 1]$, 存在 $\varphi(\tau) \in (\tau, 1)$ 使得对每个 $x, y \in C_{h,e}$, 取 $\rho_0 = E^*$, 有

$$\begin{aligned}
 &A(\tau x + (\tau - 1)e, \tau^{-1}y + (\tau^{-1} - 1)e)(t) \\
 &= \int_0^1 G(t, s)q(s)g\left(I_{0+}^{n-2}[\tau x(s) + (\tau - 1)e(s)], I_{0+}^{n-3}[\tau x(s) + (\tau - 1)e(s)], \dots, [\tau x(s) + (\tau - 1)e(s)], \right. \\
 &\quad \left. I_{0+}^{n-2}[\tau^{-1}y(s) + (\tau^{-1} - 1)e(s)], I_{0+}^{n-3}[\tau^{-1}y(s) + (\tau^{-1} - 1)e(s)], \dots, [\tau^{-1}y(s) + (\tau^{-1} - 1)e(s)]\right)ds - e(t)
 \end{aligned}$$

$$\begin{aligned}
 & I_{0+}^{n-2}[\tau^{-1}y(s) + (\tau^{-1} - 1)e(s)], I_{0+}^{n-3}[\tau^{-1}y(s) + (\tau^{-1} - 1)e(s)], \dots, [\tau^{-1}y(s) + (\tau^{-1} - 1)e(s)] \Big) ds - e(t) \\
 = & \int_0^1 G(t, s)q(s)g \left(\tau I_{0+}^{n-2}x(s) + (\tau - 1)I_{0+}^{n-2}e(s), \tau I_{0+}^{n-3}x(s) + (\tau - 1)I_{0+}^{n-3}e(s), \dots, \tau x(s) + (\tau - 1)e(s), \right. \\
 & \left. \tau^{-1}I_{0+}^{n-2}y(s) + (\tau^{-1} - 1)I_{0+}^{n-2}e(s), \tau^{-1}I_{0+}^{n-3}y(s) + (\tau^{-1} - 1)I_{0+}^{n-3}e(s), \dots, \tau^{-1}y + (\tau^{-1} - 1)e(s) \right) ds - e(t) \\
 \geq & \int_0^1 G(t, s)q(s)g \left(\tau I_{0+}^{n-2}x(s) + (\tau - 1)E^*, \tau I_{0+}^{n-3}x(s) + (\tau - 1)E^*, \dots, \tau x(s) + (\tau - 1)E^*, \right. \\
 & \left. \tau^{-1}I_{0+}^{n-2}y(s) + (\tau^{-1} - 1)E^*, \tau^{-1}I_{0+}^{n-3}y(s) + (\tau^{-1} - 1)E^*, \dots, \tau^{-1}y + (\tau^{-1} - 1)E^* \right) ds - e(t) \\
 = & \int_0^1 G(t, s)q(s)g \left(\tau I_{0+}^{n-2}x(s) + (\tau - 1)\rho_0, \tau I_{0+}^{n-3}x(s) + (\tau - 1)\rho_0, \dots, \tau x(s) + (\tau - 1)\rho_0, \right. \\
 & \left. \tau^{-1}I_{0+}^{n-2}y(s) + (\tau^{-1} - 1)\rho_0, \tau^{-1}I_{0+}^{n-3}y(s) + (\tau^{-1} - 1)\rho_0, \dots, \tau^{-1}y + (\tau^{-1} - 1)\rho_0 \right) ds - e(t) \\
 \geq & \varphi(\tau) \int_0^1 G(t, s)q(s)g(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}y(s), I_{0+}^{n-3}y(s), \dots, y(s)) ds - e(t) \\
 = & \varphi(\tau) \int_0^1 G(t, s)q(s)g(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}y(s), I_{0+}^{n-3}y(s), \dots, y(s)) ds - e(t) + \varphi(\tau)e(t) - \varphi(\tau)e(t) \\
 = & \varphi(\tau) \left[\int_0^1 G(t, s)q(s)g(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}y(s), I_{0+}^{n-3}y(s), \dots, y(s)) ds - e(t) \right] + (\varphi(\tau) - 1)e(t) \\
 = & \varphi(\tau)A(x, y)(t) + (\varphi(\tau) - 1)e(t),
 \end{aligned}$$

$$\begin{aligned}
 & B(\tau x + (\tau - 1)e, \tau^{-1}y + (\tau^{-1} - 1)e)(t) \\
 = & \int_0^1 G(t, s)q(s)\phi \left(I_{0+}^{n-2}[\tau x(s) + (\tau - 1)e(s)], I_{0+}^{n-3}[\tau x(s) + (\tau - 1)e(s)], \dots, \tau x(s) + (\tau - 1)e(s), \right. \\
 & \left. I_{0+}^{n-2}[\tau^{-1}y(s) + (\tau^{-1} - 1)e(s)], I_{0+}^{n-3}[\tau^{-1}y(s) + (\tau^{-1} - 1)e(s)], \dots, \tau^{-1}y(s) + (\tau^{-1} - 1)e(s) \right) ds - e(t) \\
 = & \int_0^1 G(t, s)q(s)\phi \left(\tau I_{0+}^{n-2}x(s) + (\tau - 1)I_{0+}^{n-2}e(s), \tau I_{0+}^{n-3}x(s) + (\tau - 1)I_{0+}^{n-3}e(s), \dots, \tau x(s) + (\tau - 1)e(s), \right. \\
 & \left. \tau^{-1}I_{0+}^{n-2}y(s) + (\tau^{-1} - 1)I_{0+}^{n-2}e(s), \tau^{-1}I_{0+}^{n-3}y(s) + (\tau^{-1} - 1)I_{0+}^{n-3}e(s), \dots, \tau^{-1}y + (\tau^{-1} - 1)e(s) \right) ds - e(t) \\
 \geq & \int_0^1 G(t, s)q(s)\phi \left(\tau I_{0+}^{n-2}x(s) + (\tau - 1)E^*, \tau I_{0+}^{n-3}x(s) + (\tau - 1)E^*, \dots, \tau x(s) + (\tau - 1)E^*, \right. \\
 & \left. \tau^{-1}I_{0+}^{n-2}y(s) + (\tau^{-1} - 1)E^*, \tau^{-1}I_{0+}^{n-3}y(s) + (\tau^{-1} - 1)E^*, \dots, \tau^{-1}y + (\tau^{-1} - 1)E^* \right) ds - e(t) \\
 = & \int_0^1 G(t, s)q(s)\phi \left(\tau I_{0+}^{n-2}x(s) + (\tau - 1)\rho_0, \tau I_{0+}^{n-3}x(s) + (\tau - 1)\rho_0, \dots, \tau x(s) + (\tau - 1)\rho_0, \right. \\
 & \left. \tau^{-1}I_{0+}^{n-2}y(s) + (\tau^{-1} - 1)\rho_0, \tau^{-1}I_{0+}^{n-3}y(s) + (\tau^{-1} - 1)\rho_0, \dots, \tau^{-1}y + (\tau^{-1} - 1)\rho_0 \right) ds - e(t) \\
 \geq & \tau \int_0^1 G(t, s)q(s)\phi(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}y(s), I_{0+}^{n-3}y(s), \dots, y(s)) ds - e(t) \\
 = & \tau \int_0^1 G(t, s)q(s)\phi(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}y(s), I_{0+}^{n-3}y(s), \dots, y(s)) ds - e(t) + \tau e(t) - \tau e(t) \\
 = & \tau \left[\int_0^1 G(t, s)q(s)\phi(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}y(s), I_{0+}^{n-3}y(s), \dots, y(s)) ds - e(t) \right] + (\tau - 1)e(t) \\
 = & \tau B(x, y)(t) + (\tau - 1)e(t).
 \end{aligned}$$

(3) 第三, 证明 $A(h, h) \in C_{h,e}, B(h, h) \in C_{h,e}$. 即证 $A(h, h) + e \in C_h, B(h, h) + e \in C_h$. 由引理 2.2, $(H_4), (H_5)$ 可以得出

$$\begin{aligned}
 A(h, h)(t) + e(t) &= \int_0^1 G(t, s)q(s)g(I_{0+}^{n-2}h(s), I_{0+}^{n-3}h(s), \dots, h(s), I_{0+}^{n-2}h(s), I_{0+}^{n-3}h(s), \dots, h(s))ds \\
 &= \int_0^1 G(t, s)q(s)g(I_{0+}^{n-2}Ms^{\alpha-n+1}, I_{0+}^{n-3}Ms^{\alpha-n+1}, \\
 &\quad \dots, Ms^{\alpha-n+1}, I_{0+}^{n-2}Ms^{\alpha-n+1}, I_{0+}^{n-3}Ms^{\alpha-n+1}, \dots, Ms^{\alpha-n+1})ds \\
 &= \int_0^1 G(t, s)q(s)g(MI_{0+}^{n-2}s^{\alpha-n+1}, MI_{0+}^{n-3}s^{\alpha-n+1}, \\
 &\quad \dots, Ms^{\alpha-n+1}, MI_{0+}^{n-2}s^{\alpha-n+1}, MI_{0+}^{n-3}s^{\alpha-n+1}, \dots, Ms^{\alpha-n+1})ds \\
 &\leq \int_0^1 \frac{t^{\alpha-n+1}}{\Gamma(\alpha-n+2)}q(s)g(M, M, \dots, M, 0, 0, \dots, 0)ds \\
 &= \frac{1}{\Gamma(\alpha-n+2)}g(M, M, \dots, M, 0, 0, \dots, 0) \int_0^1 q(s)ds \cdot t^{\alpha-n+1} \\
 &= \frac{1}{M\Gamma(\alpha-n+2)}g(M, M, \dots, M, 0, 0, \dots, 0) \int_0^1 q(s)ds \cdot h(t)
 \end{aligned}$$

和

$$\begin{aligned}
 A(h, h)(t) + e(t) &\geq \int_0^1 \rho(s)G(s, s)q(s)g(0, 0, \dots, 0, M, M, \dots, M)ds \\
 &\geq \int_0^1 \rho(s)G(s, s)q(s)\delta_0\phi(0, 0, \dots, 0, M, M, \dots, M)ds \\
 &\geq \delta_0\phi(0, 0, \dots, 0, M, M, \dots, M) \int_0^1 \rho(s)G(s, s)q(s)ds \cdot t^{\alpha-n+1} \\
 &= \frac{1}{M}\delta_0\phi(0, 0, \dots, 0, M, M, \dots, M) \int_0^1 \rho(s)G(s, s)q(s)ds \cdot h(t).
 \end{aligned}$$

令

$$\begin{aligned}
 l_1 &= \frac{1}{M}\delta_0\phi(0, 0, \dots, 0, M, M, \dots, M) \int_0^1 \rho(s)G(s, s)q(s)ds, \\
 L_1 &= \frac{1}{M\Gamma(\alpha-n+2)}g(M, M, \dots, M, 0, 0, \dots, 0) \int_0^1 q(s)ds.
 \end{aligned}$$

即 $0 < l_1 \leq L_1 < +\infty, l_1h(t) \leq A(h, h)(t) + e(t) \leq L_1h(t), t \in [0, 1]$, 因此有 $A(h, h) \in C_{h,e}$. 同样的方法有

$$B(h, h)(t) + e(t) = \int_0^1 G(t, s)q(s)\phi(I_{0+}^{n-2}h(s), I_{0+}^{n-3}h(s), \dots, h(s), I_{0+}^{n-2}h(s), I_{0+}^{n-3}h(s), \dots, h(s))ds$$

$$\begin{aligned} &\leq \int_0^1 \frac{t^{\alpha-n+1}}{\Gamma(\alpha-n+2)} q(s)\phi(M, M, \dots, M, 0, 0, \dots, 0) ds \\ &= \frac{1}{\Gamma(\alpha-n+2)} \phi(M, M, \dots, M, 0, 0, \dots, 0) \int_0^1 q(s) ds \cdot t^{\alpha-n+1} \\ &= \frac{1}{M\Gamma(\alpha-n+2)} \phi(M, M, \dots, M, 0, 0, \dots, 0) \int_0^1 q(s) ds \cdot h(t) \end{aligned}$$

和

$$\begin{aligned} B(x, x)(t) + e(t) &\geq \int_0^1 \rho(s)G(s, s)q(s)\phi(0, 0, \dots, 0, M, M, \dots, M) ds \\ &\geq \phi(0, 0, \dots, 0, M, M, \dots, M) \int_0^1 \rho(s)G(s, s)q(s) ds \cdot t^{\alpha-n+1} \\ &= \frac{1}{M} \phi(0, 0, \dots, 0, M, M, \dots, M) \int_0^1 \rho(s)G(s, s)q(s) ds \cdot h(t). \end{aligned}$$

令

$$\begin{aligned} l_2 &= \frac{1}{M} \phi(0, 0, \dots, 0, M, M, \dots, M) \int_0^1 \rho(s)G(s, s)q(s) ds, \\ L_2 &= \frac{1}{M\Gamma(\alpha-n+2)} \phi(M, M, \dots, M, 0, 0, \dots, 0) \int_0^1 q(s) ds. \end{aligned}$$

即 $0 < l_2 \leq L_2 < +\infty$, $l_2 h(t) \leq B(h, h)(t) + e(t) \leq L_2 h(t)$, $t \in [0, 1]$, 因此有 $B(h, h) \in C_{h,e}$.

(4) 最后, 证明引理2.4 中的(iv) 成立. 对每个 $x, y \in C_{h,e}$, $t \in [0, 1]$, 由 (H_4) 得出

$$\begin{aligned} A(x, y)(t) &= \int_0^1 G(t, s)q(s)g(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}y(s), I_{0+}^{n-3}y(s), \dots, y(s)) ds - e(t) \\ &\geq \delta_0 \int_0^1 G(t, s)q(s)\phi(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}y(s), I_{0+}^{n-3}y(s), \dots, y(s)) ds - e(t) - \\ &\quad \delta_0 e(t) + \delta_0 e(t) \\ &= \delta_0 \left[\int_0^1 G(t, s)q(s)\phi(I_{0+}^{n-2}x(s), I_{0+}^{n-3}x(s), \dots, x(s), I_{0+}^{n-2}y(s), I_{0+}^{n-3}y(s), \dots, y(s)) ds - e(t) \right] + \\ &\quad (\delta_0 - 1)e(t) \\ &= \delta_0 B(x, y)(t) + (\delta_0 - 1)e(t), \end{aligned}$$

即 $A(x, y) \geq \delta_0 B(x, y) + (\delta_0 - 1)e$. 因此引理2.4 中的所有条件都满足. 因此定理3.1 中的结论成立.

□

例 3.2 考虑如下BVP:

$$\begin{cases} D_{0+}^{\frac{5}{2}} u(t) + q(t)f(u(t), u'(t)) - 1 = 0, & t \in [0, 1], \\ u(0) = u'(0) = u'(1) = 0, \end{cases} \tag{7}$$

其中 $q(t) = t^{\frac{1}{2}}$, $f(u(t), u'(t)) = (1+t)[(\frac{e(t)}{E^*}u(t) + e(t))^{\frac{1}{2}} + (\frac{e(t)}{E^*}u(t) + e(t))^{\frac{1}{3}} + (\frac{e(t)}{E^*}u'(t) + e(t))^{-\frac{1}{5}} + (\frac{e(t)}{E^*}u'(t) + e(t))^{-\frac{1}{6}}]$, $E^* = \max\{e(t), I_{0+}^1 e(t) : t \in [0, 1]\} = \frac{472\Gamma(\frac{7}{2})}{2539}$.

令 $u(t) = I_{0+}^1 x(t)$, 那么方程(7)可转化为如下形式:

$$\begin{cases} D_{0+}^{\frac{3}{2}} x(t) + q(t)f(I_{0+}^1 x(t), x(t)) - 1 = 0, & t \in [0, 1], \\ x(0) = x(1) = 0, \end{cases} \quad (8)$$

其中

$$\begin{aligned} f(I_{0+}^1 x(t), x(t)) &= f(x, y) = (1+t)[(\frac{e(t)}{E^*}x + e(t))^{\frac{1}{2}} + (\frac{e(t)}{E^*}x + e(t))^{\frac{1}{3}} + (\frac{e(t)}{E^*}y + e(t))^{-\frac{1}{5}} + (\frac{e(t)}{E^*}y + e(t))^{-\frac{1}{6}}], \\ g(x, x, y, y) &= (\frac{e(t)}{E^*}x + e(t))^{\frac{1}{2}} + (\frac{e(t)}{E^*}x + e(t))^{\frac{1}{3}} + (\frac{e(t)}{E^*}y + e(t))^{-\frac{1}{5}} + (\frac{e(t)}{E^*}y + e(t))^{-\frac{1}{6}}, \\ \phi(x, x, y, y) &= t(\frac{e(t)}{E^*}x + e(t))^{\frac{1}{2}} + t(\frac{e(t)}{E^*}x + e(t))^{\frac{1}{3}} + t(\frac{e(t)}{E^*}y + e(t))^{-\frac{1}{5}} + t(\frac{e(t)}{E^*}y + e(t))^{-\frac{1}{6}}. \end{aligned}$$

对于任意的 $x, y > -E^*$, 有 $f(x, y) = g(x, x, y, y) + \phi(x, x, y, y)$, $e(t) = \frac{t^{\frac{3}{2}} - t^{\frac{5}{2}}}{\Gamma(\frac{7}{2})}$, $E^* = \max\{e(t), I_{0+}^1 e(t) : t \in [0, 1]\} = \frac{472\Gamma(\frac{7}{2})}{2539}$. 接下来, 检验定理3.1中的所有条件是否都满足.

(i) 显然, 函数 $g, \phi : [-E^*, +\infty)^4 \rightarrow (-\infty, +\infty)$ 是连续的.

(ii) 对于固定的 $y_i \in [-E^*, +\infty)$ ($i = 1, 2$), $g(x, x, y, y)$, $\phi(x, x, y, y)$ 在 $x_i \in [-E^*, +\infty)$ ($i = 1, 2$) 上是非减的; 对于固定的 $x_i \in [-E^*, +\infty)$ ($i = 1, 2$), $g(x, x, y, y)$, $\phi(x, x, y, y)$ 在 $y_i \in [-E^*, +\infty)$ ($i = 1, 2$) 上是非增的.

(iii) 对 $\tau \in (0, 1)$, $x_i, y_i \in [-E^*, +\infty)$ ($i = 1, 2$), 取 $\rho_0 = e$, $\varphi(\tau) = \tau^{\frac{1}{2}}$, 有

$$\begin{aligned} & g(\tau x + (\tau - 1)\rho_0, \tau x + (\tau - 1)\rho_0, \tau^{-1}y + (\tau^{-1} - 1)\rho_0, \tau^{-1}y + (\tau^{-1} - 1)\rho_0) \\ &= g(\tau x + (\tau - 1)e, \tau x + (\tau - 1)e, \tau^{-1}y + (\tau^{-1} - 1)e, \tau^{-1}y + (\tau^{-1} - 1)e) \\ &= (\tau \frac{e(t)}{E^*}x + (\tau - 1)e(t) + e(t))^{\frac{1}{2}} + (\tau \frac{e(t)}{E^*}x + (\tau - 1)e(t) + e(t))^{\frac{1}{3}} + (\tau^{-1} \frac{e(t)}{E^*}y + (\tau^{-1} - 1)e(t) + e(t))^{-\frac{1}{5}} \\ & \quad + (\tau^{-1} \frac{e(t)}{E^*}y + (\tau^{-1} - 1)e(t) + e(t))^{-\frac{1}{6}} \\ &= (\tau \frac{e(t)}{E^*}x + \tau e(t))^{\frac{1}{2}} + (\tau \frac{e(t)}{E^*}x + \tau e(t))^{\frac{1}{3}} + (\tau^{-1} \frac{e(t)}{E^*}y + \tau^{-1}e(t))^{-\frac{1}{5}} + (\tau^{-1} \frac{e(t)}{E^*}y + \tau^{-1}e(t))^{-\frac{1}{6}} \\ &= \tau^{\frac{1}{2}} (\frac{e(t)}{E^*}x + e(t))^{\frac{1}{2}} + \tau^{\frac{1}{3}} (\frac{e(t)}{E^*}x + e(t))^{\frac{1}{3}} + \tau^{\frac{1}{5}} (\frac{e(t)}{E^*}y + e(t))^{-\frac{1}{5}} + \tau^{\frac{1}{6}} (\frac{e(t)}{E^*}y + e(t))^{-\frac{1}{6}} \\ &\geq \tau^{\frac{1}{2}} [(\frac{e(t)}{E^*}x + e(t))^{\frac{1}{2}} + (\frac{e(t)}{E^*}x + e(t))^{\frac{1}{3}} + (\frac{e(t)}{E^*}y + e(t))^{-\frac{1}{5}} + (\frac{e(t)}{E^*}y + e(t))^{-\frac{1}{6}}] \\ &= \varphi(\tau)g(x, x, y, y). \end{aligned}$$

对于 $\tau \in (0, 1)$ 和 $x_i, y_i \in [-E^*, +\infty)$, ($i = 1, 2$), 取 $\rho_0 = e$, 有

$$\begin{aligned} & \phi(\tau x + (\tau - 1)\rho_0, \tau x + (\tau - 1)\rho_0, \tau^{-1}y + (\tau^{-1} - 1)\rho_0, \tau^{-1}y + (\tau^{-1} - 1)\rho_0) \\ &= \phi(\tau x + (\tau - 1)e, \tau x + (\tau - 1)e, \tau^{-1}y + (\tau^{-1} - 1)e, \tau^{-1}y + (\tau^{-1} - 1)e) \\ &= t[(\tau \frac{e(t)}{E^*}x + (\tau - 1)e(t) + e(t))^{\frac{1}{2}} + (\tau \frac{e(t)}{E^*}x + (\tau - 1)e(t) + e(t))^{\frac{1}{3}} + (\tau^{-1} \frac{e(t)}{E^*}y + (\tau^{-1} - 1)e(t) + e(t))^{-\frac{1}{5}} \\ & \quad + (\tau^{-1} \frac{e(t)}{E^*}y + (\tau^{-1} - 1)e(t) + e(t))^{-\frac{1}{6}}] \end{aligned}$$

$$\begin{aligned}
 &= t \left[\left(\tau \frac{e(t)}{E^*} x + \tau e(t) \right)^{\frac{1}{2}} + \left(\tau \frac{e(t)}{E^*} x + \tau e(t) \right)^{\frac{1}{3}} + \left(\tau^{-1} \frac{e(t)}{E^*} y + \tau^{-1} e(t) \right)^{-\frac{1}{5}} + \left(\tau^{-1} \frac{e(t)}{E^*} y + \tau^{-1} e(t) \right)^{-\frac{1}{6}} \right] \\
 &= t \left[\tau^{\frac{1}{2}} \left(\frac{e(t)}{E^*} x + e(t) \right)^{\frac{1}{2}} + \tau^{\frac{1}{3}} \left(\frac{e(t)}{E^*} x + e(t) \right)^{\frac{1}{3}} + \tau^{\frac{1}{5}} \left(\frac{e(t)}{E^*} y + e(t) \right)^{-\frac{1}{5}} + \tau^{\frac{1}{6}} \left(\frac{e(t)}{E^*} y + e(t) \right)^{-\frac{1}{6}} \right] \\
 &\geq t \left\{ \tau^{\frac{1}{6}} \left[\left(\frac{e(t)}{E^*} x + e(t) \right)^{\frac{1}{2}} + \left(\frac{e(t)}{E^*} x + e(t) \right)^{\frac{1}{3}} + \left(\frac{e(t)}{E^*} y + e(t) \right)^{-\frac{1}{5}} + \left(\frac{e(t)}{E^*} y + e(t) \right)^{-\frac{1}{6}} \right] \right\} \\
 &\geq \tau \left\{ t \left[\left(\frac{e(t)}{E^*} x + e(t) \right)^{\frac{1}{2}} + \left(\frac{e(t)}{E^*} x + e(t) \right)^{\frac{1}{3}} + \left(\frac{e(t)}{E^*} y + e(t) \right)^{-\frac{1}{5}} + \left(\frac{e(t)}{E^*} y + e(t) \right)^{-\frac{1}{6}} \right] \right\} \\
 &= \tau \phi(x, x, y, y).
 \end{aligned}$$

(iv) 取 $\rho_0 = e, \delta_0 = 1 > 0$. 那么

$$\begin{aligned}
 g(x, x, y, y) &= \left(\frac{e(t)}{E^*} x + \rho_0 \right)^{\frac{1}{2}} + \left(\frac{e(t)}{E^*} x + \rho_0 \right)^{\frac{1}{3}} + \left(\frac{e(t)}{E^*} y + \rho_0 \right)^{-\frac{1}{5}} + \left(\frac{e(t)}{E^*} y + \rho_0 \right)^{-\frac{1}{6}} \\
 &= \left(\frac{e(t)}{E^*} x + e(t) \right)^{\frac{1}{2}} + \left(\frac{e(t)}{E^*} x + e(t) \right)^{\frac{1}{3}} + \left(\frac{e(t)}{E^*} y + e(t) \right)^{-\frac{1}{5}} + \left(\frac{e(t)}{E^*} y + e(t) \right)^{-\frac{1}{6}} \\
 &\geq 1 \left\{ t \left[\left(\frac{e(t)}{E^*} x + e(t) \right)^{\frac{1}{2}} + \left(\frac{e(t)}{E^*} x + e(t) \right)^{\frac{1}{3}} + \left(\frac{e(t)}{E^*} y + e(t) \right)^{-\frac{1}{5}} + \left(\frac{e(t)}{E^*} y + e(t) \right)^{-\frac{1}{6}} \right] \right\} \\
 &= \delta_0 \phi(x, x, y, y).
 \end{aligned}$$

(v) 取 $M = 1.51 > \frac{1}{(\frac{5}{2}-3+1)\Gamma(\frac{5}{2}-3+3)}$,

$$\begin{aligned}
 g(M, M, 0, 0) &< (1.51 + 1)^{\frac{1}{2}} + (1.51 + 1)^{\frac{1}{3}} + 1 + 1 = 4.9433 < +\infty, \\
 \phi(M, M, 0, 0) &< (1.51 + 1)^{\frac{1}{2}} + (1.51 + 1)^{\frac{1}{3}} + 1 + 1 = 4.9433 < +\infty, \\
 \phi(0, 0, M, M) &> 0.
 \end{aligned}$$

因此, 定理3.1 中的假设全部满足. 结合引理2.3, BVP 7 存在唯一的非平凡解. 此外, 设置以下序列:

$$\begin{aligned}
 \omega_n(t) &= \int_0^1 G(t, s) \left(\left(\frac{e(s)}{E^*} \omega_{n-1}(s) + e(s) \right)^{\frac{1}{2}} + \left(\frac{e(s)}{E^*} \omega_{n-1}(s) + e(s) \right)^{\frac{1}{3}} + \left(\frac{e(s)}{E^*} \tau_{n-1}(s) + e(s) \right)^{-\frac{1}{5}} + \left(\frac{e(s)}{E^*} \tau_{n-1}(s) + e(s) \right)^{-\frac{1}{6}} \right) ds \\
 &\quad + \int_0^1 G(t, s) \left(t \left(\frac{e(s)}{E^*} \omega_{n-1}(s) + e(s) \right)^{\frac{1}{2}} + t \left(\frac{e(s)}{E^*} \omega_{n-1}(s) + e(s) \right)^{\frac{1}{3}} + t \left(\frac{e(s)}{E^*} \tau_{n-1}(s) + e(s) \right)^{-\frac{1}{5}} + s \left(\frac{e(s)}{E^*} \tau_{n-1}(s) + e(s) \right)^{-\frac{1}{6}} \right) ds \\
 &\quad + \frac{t^{\frac{3}{2}} - t^{\frac{5}{2}}}{\Gamma(\frac{7}{2})}, \quad n = 1, 2, \dots
 \end{aligned}$$

和

$$\begin{aligned}
 \tau_n(t) &= \int_0^1 G(t, s) \left(\left(\frac{e(s)}{E^*} \tau_{n-1}(s) + e(s) \right)^{\frac{1}{2}} + \left(\frac{e(s)}{E^*} \tau_{n-1}(s) + e(s) \right)^{\frac{1}{3}} + \left(\frac{e(s)}{E^*} \omega_{n-1}(s) + e(s) \right)^{-\frac{1}{5}} + \left(\frac{e(s)}{E^*} \omega_{n-1}(s) + e(s) \right)^{-\frac{1}{6}} \right) ds \\
 &\quad + \int_0^1 G(t, s) \left(t \left(\frac{e(s)}{E^*} \tau_{n-1}(s) + e(s) \right)^{\frac{1}{2}} + t \left(\frac{e(s)}{E^*} \tau_{n-1}(s) + e(s) \right)^{\frac{1}{3}} + t \left(\frac{e(s)}{E^*} \omega_{n-1}(s) + e(s) \right)^{-\frac{1}{5}} + s \left(\frac{e(s)}{E^*} \omega_{n-1}(s) + e(s) \right)^{-\frac{1}{6}} \right) ds
 \end{aligned}$$

$$t\left(\frac{e(s)}{E^*}\tau_{n-1}(s) + e(s)\right)^{\frac{1}{3}} + t\left(\frac{e(s)}{E^*}\omega_{n-1}(s) + e(s)\right)^{-\frac{1}{5}} + s\left(\frac{e(s)}{E^*}\omega_{n-1}(s) + e(s)\right)^{-\frac{1}{6}} \Big) ds + \frac{t^{\frac{3}{2}} - t^{\frac{5}{2}}}{\Gamma(\frac{7}{2})}, \quad n = 1, 2, \dots,$$

对于任意给定的初值 $\omega_0, \tau_0 \in C_{h,e}$, 凡 $t \in [0, 1]$, 我们有 $\{\omega_n(t)\}$ 和 $\{\tau_n(t)\}$ 都一致收敛于 x^* . 因此, 定理3.1 中的假设成立. 结合引理2.3, BVP 7 存在唯一的非平凡解.

参考文献

- [1] Gaul, L., Klein, P. and Kemple, S. (1991) Damping Description Involving Fractional Operators. *Mechanical Systems and Signal Processing*, **5**, 81-88.
[https://doi.org/10.1016/0888-3270\(91\)90016-X](https://doi.org/10.1016/0888-3270(91)90016-X)
- [2] Miller, K.S. and Ross, B. (1993) An Introduction to the Fractional Calculus and Fractional Differential Equations. Wiley, New York.
- [3] Glöckle, W.G. and Nonnenmacher, T.F. (1995) A Fractional Calculus Approach to Self-Similar Protein Dynamics. *Biophysical Journal*, **68**, 46-53.
[https://doi.org/10.1016/S0006-3495\(95\)80157-8](https://doi.org/10.1016/S0006-3495(95)80157-8)
- [4] Kilbas, A.A., Srivastava, H.M. and Trujillo J.J., Eds. (2006) Theory and Applications of Fractional Differential Equations. In: *North-Holland Mathematics Studies*, Elsevier, Amsterdam, 204.
- [5] Ouahab, A. (2008) Some Results for Fractional Boundary Value Problem of Differential Inclusions. *Nonlinear Analysis: Theory, Methods & Applications*, **69**, 3877-3896.
<https://doi.org/10.1016/j.na.2007.10.021>
- [6] Lazarević, M.P. and Spasić, A.M. (2009) Finite-Time Stability Analysis of Fractional Order Time-Delay Systems: Gronwall's Approach. *Mathematical and Computer Modelling*, **49**, 475-481. <https://doi.org/10.1016/j.mcm.2008.09.011>
- [7] Hussein, A.H.S. (2009) On the Fractional Order m-Point Boundary Value Problem in Reflexive Banach Spaces and Weak Topologies. *Journal of Computational and Applied Mathematics*, **224**, 565-572. <https://doi.org/10.1016/j.cam.2008.05.033>
- [8] Benchohra, M., Hamani, S. and Ntouyas, S.K. (2009) Boundary Value Problems for Differential Equations with Fractional Order and Nonlocal Conditions. *Nonlinear Analysis: Theory, Methods and Applications*, **71**, 2391-2396. <https://doi.org/10.1016/j.na.2009.01.073>
- [9] Cabada, A. and Wang, G.T. (2012) Positive Solutions of Nonlinear Fractional Differential Equations with Integral Boundary Value Conditions. *Journal of Mathematical Analysis and Applications*, **389**, 403-411. <https://doi.org/10.1016/j.jmaa.2011.11.065>

- [10] Xu, X.J. and Fei, X.L. (2012) The Positive Properties of Green's Function for Three Point Boundary, Value Problems of Nonlinear Fractional Differential Equations and Its Applications. *Communications in Nonlinear Science and Numerical Simulation*, **17**, 1555-1565. <https://doi.org/10.1016/j.cnsns.2011.08.032>
- [11] Zhang, X.G., Liu, L.S. and Wu, Y.H. (2012) The Eigenvalue problem for a Singular Higher Order Fractional Differential Equation Involving Fractional Derivatives. *Applied Mathematics and Computation*, **218**, 8526-8536. <https://doi.org/10.1016/j.amc.2012.02.014>
- [12] Wang, Y., Liu, L.S., Zhang, X.G., et al. (2015) Positive Solutions of an Abstract Fractional Semipositone Differential System Model for Bioprocesses of HIV Infection. *Applied Mathematics and Computation*, **258**, 312-324. <https://doi.org/10.1016/j.amc.2015.01.080>
- [13] Zhang, S.Q. (2010) Positive Solutions to Singular Boundary Value Problem for Nonlinear Fractional Differential Equation. *Computers and Mathematics with Applications*, **59**, 1300-1309. <https://doi.org/10.1016/j.camwa.2009.06.034>
- [14] Sang, Y.B. and Ren, Y. (2009) Nonlinear Sum Operator Equations and Applications to Elastic Beam Equation and Fractional Differential Equation. *Boundary Value Problems*, **2019**, Article No. 49. <https://doi.org/10.1186/s13661-019-1160-x>
- [15] Zhai, C. and Anderson, D.R. (2011) A Sum Operator Equation and Applications to Nonlinear Elastic Beam Equations and Lane-Emden-Fowler Equations. *Journal of Mathematical Analysis and Applications*, **375**, 388-400. <https://doi.org/10.1016/j.jmaa.2010.09.017>
- [16] Cabrera, I.J., López, B. and Sadarangani, K. (2018) Existence of Positive Solutions for the Nonlinear Elastic Beam Equation via a Mixed Monotone Operator. *Journal of Computational and Applied Mathematics*, **327**, 306-313. <https://doi.org/10.1016/j.cam.2017.04.031>
- [17] Guo, D.J. and Lakshmikantham, V. (1987) Coupled Fixed Points of Nonlinear Operators with Applications. *Nonlinear Analysis*, **11**, 623-632. [https://doi.org/10.1016/0362-546X\(87\)90077-0](https://doi.org/10.1016/0362-546X(87)90077-0)
- [18] Bhaskar, T.G. and Lakshmikantham, V. (2006) Fixed Point Theorems in Partially Ordered Metric Spaces and Applications. *Nonlinear Analysis: Theory, Methods & Applications*, **65**, 1379-1393. <https://doi.org/10.1016/j.na.2005.10.017>
- [19] Li, X.C. and Zhao, Z.Q. (2011) On a Fixed Point Theorem of Mixed Monotone Operators and Applications. *Electronic Journal of Qualitative Theory of Differential Equations*, **94**, 1-7. <https://doi.org/10.14232/ejqtde.2011.1.94>
- [20] Liu, L.S., Zhang, X.Q., Jiang, J., et al. (2006) The Unique Solution of a Class of Sum Mixed Monotone Operator Equations and Its Application to Fractional Boundary Value Problems. *Journal of Nonlinear Science and Applications*, **9**, 2943-2958.
- [21] Guo, D.J. (2000) Partial Order Methods in Nonlinear Analysis. Shandong Science and Technology Press, Jinan.